Flex Pro Tethered Controller

Remote Control Equipment
Instruction Manual

MAGNETEK

CE

198-00132 R05
April 2019

SERVICE INFORMATION

Your New Remote Control System

Thank you for your purchase of Magnetek's Flex Pro Tethered Controller. Without a doubt, our Flex Pro systems are the ultimate solution for providing precise, undeterred, and safe control of your material.

If your product ever needs modification or service, please contact one of our representatives at the following locations:

U.S. Service Information

For questions regarding service or technical information contact:
1-866-MAG-SERV
(1-866-624-7378)

International Service

262-783-3500

World Headquarters:

Magnetek, Inc.
N49 W13650 Campbell Drive
Menomonee Falls, WI 53051

Telephone: 800-288-8178
Website: www.magnetek.com
E-mail: mhcustomerservice@magnetek.com

Fax Numbers:

Main: 800-298-3503
Sales: 262-783-3510
Service: 262-783-3508

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161 Orenda Road
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Phone: 800-792-7253
Fax: 905-828-5707
416-424-7617 (24/7 Service pager)

EU Market Contact:
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Mile Road
Bedford, MK42 9TW UK
Phone: +44-1234-349191

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1 PREFACE AND SAFETY

1.1 PRODUCT SAFETY INFORMATION

Magnetek, Inc. (Magnetek) offers a broad range of radio remote control products, control products and adjustable frequency drives, and industrial braking systems for material handling applications. This manual has been prepared by Magnetek to provide information and recommendations for the installation, use, operation and service of Magnetek's material handling products and systems (Magnetek Products). Anyone who uses, operates, maintains, services, installs or owns Magnetek Products should know, understand and follow the instructions and safety recommendations in this manual for Magnetek Products.

The recommendations in this manual do not take precedence over any of the following requirements relating to cranes, hoists lifting devices or other material handling equipment which use or include Magnetek Products:

- Instructions, manuals, and safety warnings of the manufacturers of the equipment where the radio system is used,
- Plant safety rules and procedures of the employers and the owners of facilities where the Magnetek Products are being used,
- Regulations issued by the Occupational Health and Safety Administration (OSHA),
- Applicable local, state or federal codes, ordinances, standards and requirements, or
- Safety standards and practices for the industries in which Magnetek Products are used.

This manual does not include or address the specific instructions and safety warnings of these manufacturers or any of the other requirements listed above. It is the responsibility of the owners, users and operators of the Magnetek Products to know, understand and follow all of these requirements. It is the responsibility of the employer to make its employees aware of all of the above listed requirements and to make certain that all operators are properly trained. **No one should use Magnetek Products prior to becoming familiar with and being trained in these requirements and the instructions and safety recommendations in this manual**.

WARRANTY INFORMATION

FOR INFORMATION ON MAGNETEK'S PRODUCT WARRANTIES BY PRODUCT TYPE, PLEASE VISIT WWW.MAGNETEK.COM.

2 INTRODUCTION

The Flex remote control systems are designed for control of industrial equipment and mobile machinery such as overhead traveling cranes, construction equipment, forestry equipment, mining equipment, rail equipment, drilling and trenching equipment, agriculture equipment, electric hoists, winches, monorails, conveyor belts, mining equipment and other material handling equipment where hardwired remote control is preferred.

List of notable features include:

- **Over one million unique ID codes (20bit)** – Each and every Flex system has its own unique ID code; no repeats.
- **Advanced controls** – The Flex system utilizes advanced microprocessor controls with 16-bit CRC which provides ultra-fast, safe, precise, and error-free encoding and decoding.
- **Unique I-CHIP design** – The I-CHIP functions in a way that is very similar to SIM cards used on mobile phones, with the ability to transfer system information and settings from one transmitter to another without the hassle of resetting the spares.
- **Reliable push buttons** – The in-house designed push buttons are rated for more than one million press cycles.
- **Ultra-durable nylon and fiberglass composite enclosures** – Highly resistant to breakage and deformation even in the most abusive environments.
- **Full compliance** – All systems are fully compliant with the European Directives (Safety, EMC, R&TTE, and Machinery) and Industry Canada Specifications (IC).

3 REMOTE CONTROLLED SAFETY

WARNINGS and CAUTIONS

Throughout this document WARNING and CAUTION statements have been deliberately placed to highlight items critical to the protection of personnel and equipment.

WARNING – A warning highlights an essential operating or maintenance procedure, practice, etc. which if not strictly observed, could result in injury or death of personnel, or long term physical hazards. Warnings are highlighted as shown below:

WARNING

CAUTION – A caution highlights an essential operating or maintenance procedure, practice, etc. which if not strictly observed, could result in damage to, or destruction of equipment, or loss of functional effectiveness. Cautions are highlighted as shown below:

CAUTION

WARNINGS and CAUTIONS SHOULD NEVER BE DISREGARDED.

The safety rules in this section are not intended to replace any rules or regulations of any applicable local, state, or federal governing organizations. Always follow your local lockout and tagout procedure when maintaining any radio equipment. The following information is intended to be used in conjunction with other rules or regulations already in existence. It is important to read all of the safety information contained in this section before installing or operating the Remote Control System.

WARNING

PRIOR TO INSTALLATION AND OPERATION OF THIS EQUIPMENT, READ AND DEVELOP AN UNDERSTANDING OF THE CONTENTS OF THIS MANUAL AND THE OPERATION MANUAL OF THE EQUIPMENT OR DEVICE TO WHICH THIS EQUIPMENT WILL BE INTERFACED. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

FOLLOW YOUR LOCAL LOCKOUT TAGOUT PROCEDURE BEFORE MAINTAINING ANY REMOTE CONTROLLED EQUIPMENT. ALWAYS REMOVE ALL ELECTRICAL POWER FROM THE EQUIPMENT BEFORE ATTEMPTING ANY INSTALLATION PROCEDURES. DE-ENERGIZE AND TAGOUT ALL SOURCES OF ELECTRICAL POWER BEFORE TOUCH-TESTING ANY EQUIPMENT. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

AFTER INSTALLATION BE SURE TO VERIFY THAT THE TRANSMITTER IS NOT INTERFERING WITH OTHER EQUIPMENT IN THE AREA. ALSO VERIFY THAT OTHER EQUIPMENT IS NOT INTERFERING WITH THE TRANSMITTER AND ITS ASSOCIATED EQUIPMENT. FAILURE TO FOLLOW THESE WARNINGS COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

3.1 GENERAL

Radio controlled equipment operates in several directions. Quite frequently, the equipment is operated in areas where people are working in close proximity to the equipment. **The operator must exercise extreme caution at all times**. Workers must constantly be alert to avoid accidents. The following recommendations have been included to indicate how careful and thoughtful actions may prevent injuries, damage to equipment, or even save a life.

3.2 PERSONS AUTHORIZED TO OPERATE REMOTE CONTROLLED CRANES

Only properly trained persons designated by management should be permitted to operate radio controlled equipment.

Radio controlled equipment should not be operated by any person who cannot read or understand signs, notices and operating instructions that pertain to the equipment.

Radio controlled equipment should not be operated by any person with insufficient eyesight or hearing or by any person who may be suffering from a disorder or illness, is taking any medication that may cause loss of equipment control, or is under the influence of alcohol or drugs.

3.3 SAFETY INFORMATION AND RECOMMENDED TRAINING FOR REMOTE CONTROLLED EQUIPMENT OPERATORS

Anyone being trained to operate remote controlled equipment should possess as a minimum the following knowledge and skills before using the remote controlled equipment.

The operator should:

- have knowledge of hazards pertaining to equipment operation
- have knowledge of safety rules for radio controlled equipment
- have the ability to judge distance of moving objects
- know how to properly test prior to operation
- be trained in the safe operation of the radio transmitter as it pertains to the equipment being operated
- have knowledge of the use of equipment warning lights and alarms
- have knowledge of the proper storage space for a radio control transmitter when not in use
- be trained in transferring a radio control transmitter to another person
- be trained how and when to report unsafe or unusual operating conditions
- test the transmitter emergency stop and all warning devices prior to operation; testing should be done on each shift, without a load
- be thoroughly trained and knowledgeable in proper and safe operation of the equipment that utilizes the radio control
- know how to keep the operator and other people clear of hazardous areas
- know and follow the local lockout and tagout procedures when servicing radio controlled equipment
- know and follow all applicable operating and maintenance manuals, safety procedures, regulatory requirements, and industry standards and codes

The operator shall not:

- operate the equipment if the direction of travel or function engaged does not agree with what is indicated on the controller
- operate any damaged or malfunctioning equipment
- change any settings or controls without authorization and proper training
- remove or obscure any warning or safety labels or tags
- leave power on the radio controlled equipment when the equipment is not in operation
- operate any equipment using a damaged controller because the unit may be unsafe
- operate manual motions with other than manual power
- operate radio controlled equipment when low battery indicator is on

WARNING

THE OPERATOR SHOULD NOT ATTEMPT TO REPAIR ANY RADIO CONTROLLER. IF ANY PRODUCT PERFORMANCE OR SAFETY CONCERNS ARE OBSERVED, THE EQUIPMENT SHOULD IMMEDIATELY BE TAKEN OUT OF SERVICE AND BE REPORTED TO THE SUPERVISOR. DAMAGED AND INOPERABLE RADIO CONTROLLER EQUIPMENT SHOULD BE RETURNED TO MAGNETEK FOR EVALUATION AND REPAIR. FAILURE TO FOLLOW THIS WARNING COULD RESULT IN SERIOUS INJURY OR DEATH AND DAMAGE TO EQUIPMENT.

3.4 CONTROLLER UNIT

Controller switches should never be mechanically blocked ON or OFF. When not in use, the operator should turn the controller OFF. A secure storage space should be provided for the controller unit, and the controller unit should always be placed there when not in use. This precaution will help prevent unauthorized people from operating the material handling equipment.

Spare controllers should be stored in a secure storage space and only removed from the storage space after the current controller in use has been turned OFF, taken out of the service area and secured.

3.5 PRE-OPERATION TEST

At the start of each work shift, or when a new operator takes control of the crane, operators should do, as a minimum, the following steps before making lifts with any crane or hoist:

Test all warning devices.

Test all direction and speed controls.

Test the controller emergency stop.

3.6 SPECIFIC SYSTEM WARNINGS

Below are some specific operating safety tips that should be strictly followed when operating a Flex Pro system:

1. Check the Status LED on the controller for any signs of irregularities (refer to page 22).

4 GENERAL CONTROLLER INFORMATION

4.1 EXTERNAL ILLUSTRATION (Pro 12 Configuration)

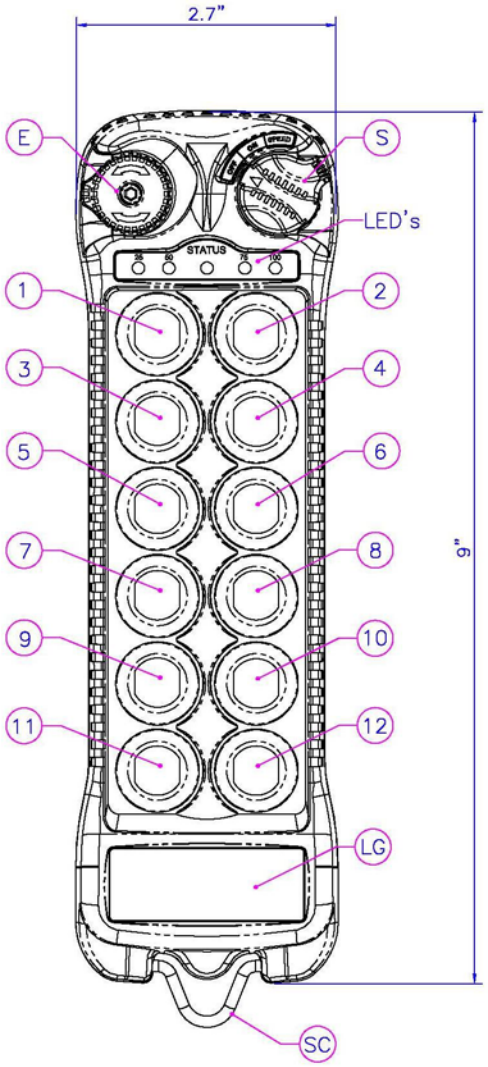


Figure 1

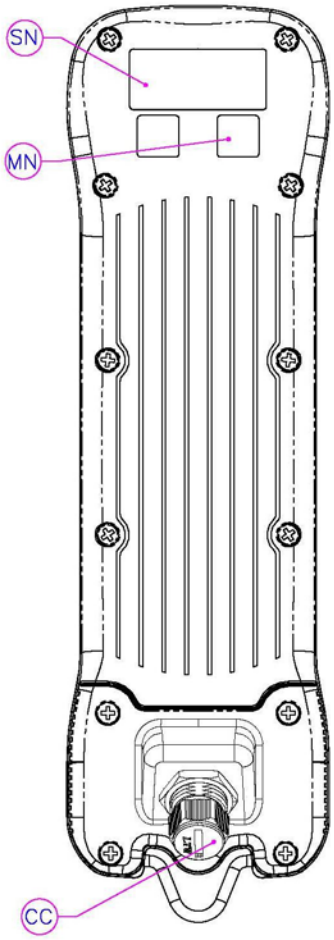


Figure 2

E.	Emergency Stop Button	6.	Push Button #6	SC.	Strap Ring
S.	Removable Power Key Switch	7.	Push Button #7	SN.	System Information
1.	Push Button #1	8.	Push Button #8	CC.	CAN Connector
2.	Push Button #2	9.	Push Button #9	MN.	Crane Number
3.	Push Button #3	10.	Push Button #10		
4.	Push Button #4	11.	Push Button #11		
5.	Push Button #5	12.	Push Button #12		

NOTE: Push buttons #9 through #12 are not present on the Flex Pro 8 Module.

4.2 INTERNAL ILLUSTRATION (Pro 12 Configuration)

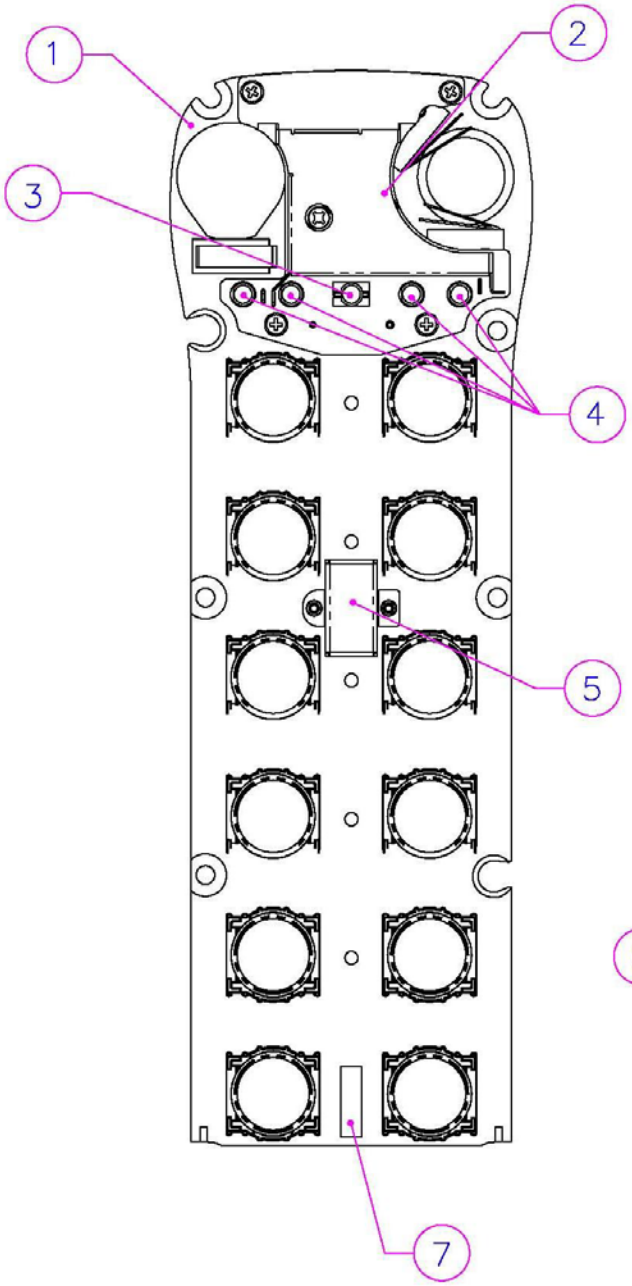


Figure 3

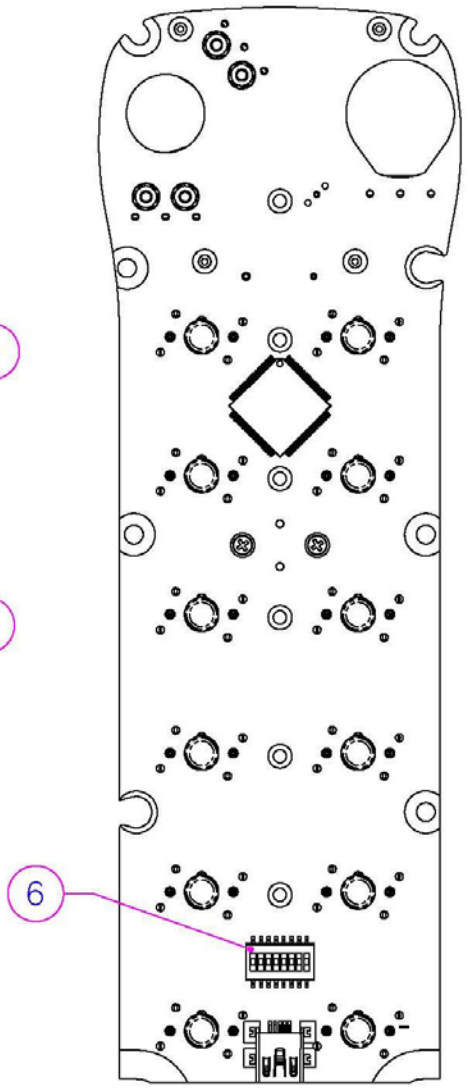


Figure 4

1. Encoder Board
2. CAN Module
3. Status LED Display
4. Function LED Displays
5. I-CHIP
6. Dip Switch
7. CAN Connector

NOTE: The Flex Pro 8 Module will differ slightly.

4.3 TYPES OF BUTTONS

The buttons used on the Flex Pro tethered controller are fully proportional, stepless push buttons with an output that varies 0-100% (based on how far the button is depressed). It is possible to model the stepless buttons as an On/Off momentary switch, On/Off latched switch, 2 Speed button, or a 3 Speed button. This modeling is done on the receiver end of the system. Please consult the factory for more information.

4.4 ADJUSTABLE SPEED CONTROL

The proportional buttons normally operate on a scale from 0-100%, but can also be scaled down to operate linearly from 0-75%, 0-50%, or 0-25% over the full motion of the button. This gives the user more control over lower speeds. To adjust the speed control settings, press and hold the Start button, then press push button 1 or push button 2 to decrement/increment the range percentage. The red LEDs, which indicate the Speed Setting, will then change to reflect the current setting.

Start +	Speed control setting
PB1	Decrement Speed Control
PB2	Increment Speed Control

Figure 5

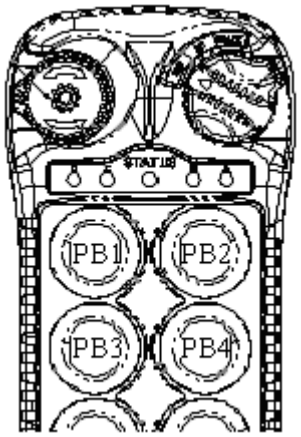


Figure 6

5 DIP SWITCH SETTINGS

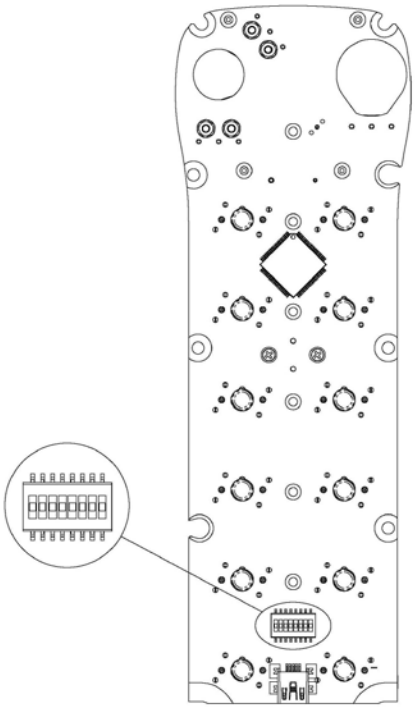


Figure 7

5.1 INACTIVITY TIME-OUT TIMER

Bits 6 and 7 on the dip switch allows the user to define a time after which, if no buttons on the controller are pressed, the Flex Pro tethered controller will send an OFF command to the equipment and power down. To restart, the user must turn the On/Off/Start switch to the Off position, then back to On again to resume operation.

Time Out	Dip switch Setting
5 minutes	01
10 minutes	10
15 minutes	11
Never shut off	00

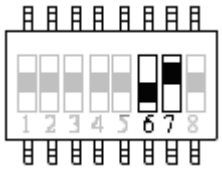


Figure 8

6 SETUP

6.1 INSTALLATION OF TETHERED CONTROLLER CABLE

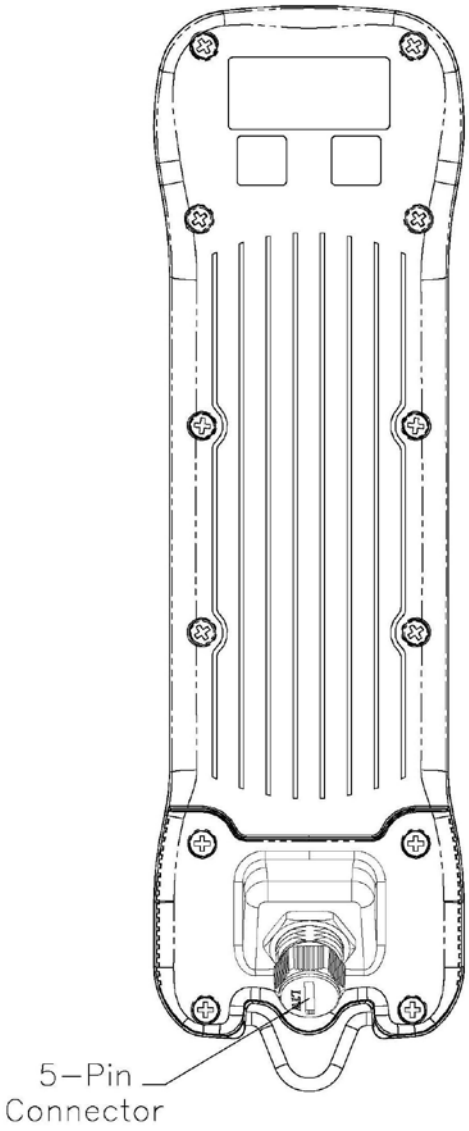
The tethered controller cable is attached to the CAN connector on the controller by lining up the alignment groove and inserting the plug into the CAN connector receptacle. Twist the locking ring on the CAN plug clockwise to tighten it down and prevent accidental disengagement.

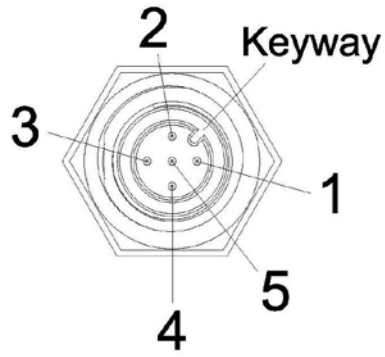
6.2 UNIT POWER

Section 6.3 shows the connections to provide power to the unit. The Flex Pro tethered controller has an input voltage range of 7.0 - 36VDC. For applications that operate at voltages above 36VDC, a voltage regulator will need to be installed to regulate the voltage to a value that is accepted by the Flex Pro tethered controller.

When connecting the Flex Pro tethered controller to a Magnetek receiver, the receiver does not provide power to the tethered controller. As such, the tethered controller will need to be wired to another power source. Typically Magnetek will provide a cable with flying leads that is used to wire the tethered controller to the receiver. The power and ground portions of this cable will need to be connected to an external power source for the tethered controller to properly operate.

6.3 CAN CONNECTOR PINOUT





CONNECTOR PINOUT (MALE PIN CONNECTOR)	
5–PIN CONNECTOR	FUNCTION
PIN 1	CAN–H
PIN 2	GND
PIN 3	POWER
PIN 4	CAN–L
PIN 5	NOT USED

6.4 J9139 PROTOCOL

The standard J1939 messages that the Flex Pro tethered controller transmits are shown below. For custom messaging, consult the factory.

PGN **65325 (FF2D hex)** **through** **65327 (FF2F hex)**	**Source Address** **169 (A9 hex) Transmitter**
Transmission Repetition Rate	50ms
Transmission Timeout	200ms
Data Length	8 bytes
Data Page	0
Priority	3

PGN	**65325 (FF2D hex)**							
Source Address	**169 (A9 hex)**							
1st PGN / SA	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Byte 1	7	6	5	4	3	2	1	0
Byte 2	5	4	3	2	1	0	9	8
Byte 3	3	2	1	0	9	8	7	6
Byte 4	1	0	9	8	7	6	5	4
Byte 5	9	8	7	6	5	4	3	2
Byte 6	7	6	5	4	3	2	1	0
Byte 7	5	4	3	2	1	0	9	8
Byte 8	1	0	1	0	9	8	7	6

Output 1	10 bit 0-to-1000
Output 2	10 bit 0-to-1000
Output 3	10 bit 0-to-1000
Output 4	10 bit 0-to-1000
Output 5	10 bit 0-to-1000
Output 6	10 bit 0-to-1000
E-Stop Command	00=off 01=on
Start/Horn	00=off 01=on

PGN	65326 (FF2E hex)							
Source Address	169 (A9 hex)							
2nd PGN / SA	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Byte 1	7	6	5	4	3	2	1	0
Byte 2	5	4	3	2	1	0	9	8
Byte 3	3	2	1	0	9	8	7	6
Byte 4	1	0	9	8	7	6	5	4
Byte 5	9	8	7	6	5	4	3	2
Byte 6	7	6	5	4	3	2	1	0
Byte 7	5	4	3	2	1	0	9	8
Byte 8	1	1	1	1	9	8	7	6

Output 7	10 bit 0-to-1000
Output 8	10 bit 0-to-1000
Output 9	10 bit 0-to-1000
Output 10	10 bit 0-to-1000
Output 11	10 bit 0-to-1000
Output 12	10 bit 0-to-1000

PGN	65327 (FF2F hex)							
Source Address	169 (A9 hex)							
3rd PGN / SA	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Byte 1	1	1	1	1	1	1	1	1
Byte 2	1	1	1	1	1	1	1	1
Byte 3	1	1	1	1	1	1	1	1
Byte 4	1	1	1	1	1	1	1	1
Byte 5	1	1	1	1	1	1	1	1
Byte 6	1	1	1	1	1	1	1	1
Byte 7	1	1	1	0	1	0	1	1
Byte 8	7	6	5	4	3	2	1	0

This is an optional PGN which will send any custom user alarms

User Alarm Enable Indication if User Alarm Input Field should be read or not

User Alarm Enable	00=off 01=on
User Alarm Condition	01=set 10=clear
User Alarm Input	8 bit 0-to-255

6.5 CANOpen PROTOCOL

The standard CANOpen messages that the Flex Pro tethered controller transmits are shown below. For custom messaging, consult the factory.

		Transmit PDO 1							
		CANopen 8bit Digital Inputs (1-8)							
		Magnetek Device Transmit							
		CAN ID				Node Id + 0x180			
		Transmission Repetition Rate				50ms			
		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CANopen 8bit Digital Input 1	Byte 1	0	0	0	0	3	2	1	0
CANopen 8bit Digital Input 2	Byte 2	7	6	5	4	3	2	1	0
CANopen 8bit Digital Input 3	Byte 3	7	6	5	4	3	2	1	0
CANopen 8bit Digital Input 4	Byte 4	7	6	5	4	3	2	1	0
CANopen 8bit Digital Input 5	Byte 5	7	6	5	4	3	2	1	0
CANopen 8bit Digital Input 6	Byte 6	7	6	5	4	3	2	1	0
CANopen 8bit Digital Input 7	Byte 7	7	6	5	4	3	2	1	0
CANopen 8bit Digital Input 8	Byte 8	7	6	5	4	3	2	1	0

Values:	
Power Down Reason	4 bits
Reserved	1 bit
Start/MLC (momentary)	1 bit
Commands Valid (see notes)	1 bit
Stop Output (On for operational state)	1 bit
(not used)	8 individual digital bits
(not used)	8 individual digital bits
(not used)	8 individual digital bits
(not used)	8 individual digital bits
(not used)	8 individual digital bits
(not used)	8 individual digital bits
LED 100, 75, 50 25	8 individual digital bits

		Transmit PDO 2							
		CANopen 16bit signed analog Inputs (1-4)							
		Magnetek Device Transmit							
		CAN ID				Node Id + 0x181			
		Transmission Repetition Rate				50ms			
		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CANopen 16bit Analog Input 1	Byte 1	7	6	5	4	3	2	1	0
	Byte 2	15	14	13	12	11	10	9	8
CANopen 16bit Analog Input 2	Byte 3	7	6	5	4	3	2	1	0
	Byte 4	15	14	13	12	11	10	9	8
CANopen 16bit Analog Input 3	Byte 5	7	6	5	4	3	2	1	0
	Byte 6	15	14	13	12	11	10	9	8
CANopen 16bit Analog Input 4	Byte 7	7	6	5	4	3	2	1	0
	Byte 8	15	14	13	12	11	10	9	8

Values:	
Button1	0-250
Button2	0-250
Button3	0-250
Button4	0-250

		Transmit PDO 3							
		CANopen 16bit signed analog Inputs (5-8)							
		Magnetek Device Transmit							
		CAN ID				Node Id + 0x182			
		Transmission Repetition Rate				50ms			
		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CANopen 16bit Analog Input 5	Byte 1	7	6	5	4	3	2	1	0
	Byte 2	15	14	13	12	11	10	9	8
CANopen 16bit Analog Input 6	Byte 3	7	6	5	4	3	2	1	0
	Byte 4	15	14	13	12	11	10	9	8
CANopen 16bit Analog Input 7	Byte 5	7	6	5	4	3	2	1	0
	Byte 6	15	14	13	12	11	10	9	8
CANopen 16bit Analog Input 8	Byte 7	7	6	5	4	3	2	1	0
	Byte 8	15	14	13	12	11	10	9	8

Values:	
Button5	0-250
Button6	0-250
Button7	0-250
Button8	0-250

		Transmit PDO 4						
		CANopen 16bit signed analog Inputs (9-12)						
		Magnetek Device Transmit						
		CAN ID				Node Id + 0x183		
		Transmission Repetition Rate				50ms		
		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CANopen 16bit Analog Input 9	Byte 1	7	6	5	4	3	2	1	0
	Byte 2	15	14	13	12	11	10	9	8
CANopen 16bit Analog Input 10	Byte 3	7	6	5	4	3	2	1	0
	Byte 4	15	14	13	12	11	10	9	8
CANopen 16bit Analog Input 11	Byte 5	7	6	5	4	3	2	1	0
	Byte 6	15	14	13	12	11	10	9	8
CANopen 16bit Analog Input 12	Byte 7	7	6	5	4	3	2	1	0
	Byte 8	15	14	13	12	11	10	9	8

Values:	
Button9	0-250
Button10	0-250
Button11	0-250
Button12	0-250

		Configure Heartbeat Timer - SDO Download 1017sub0						
		Set heartbeat message timer in mS						
		Magnetek Device Receive						
		CAN ID				Node Id + 0x600		
		Transmission Repetition Rate				single shot		
		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
SDO Download Command	Byte 1	0x22							
CANopen Object Index	Byte 2	0x1017 (Producer Heartbeat Time)							
	Byte 3								
CANopen Object SubIndex	Byte 4	0x00 (Producer Heartbeat Time)							
CANopen Object Value	Byte 5	Value for heartbeat message time in milliseconds							
	Byte 6								
	Byte 7								
	Byte 8								

7 OPERATING PROCEDURE

7.1 GENERAL OPERATING PROCEDURE

1. Reset the red emergency stop button located on the top left hand side of the controller handset by rotating it either clockwise or counter clockwise. The red button will pop up.

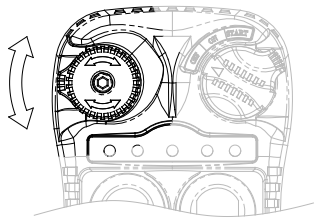


Figure 9

2. Turn on the controller power by inserting the black-colored key into the power key slot located on the top right hand side of the controller handset and rotate it clockwise to the “On” position.

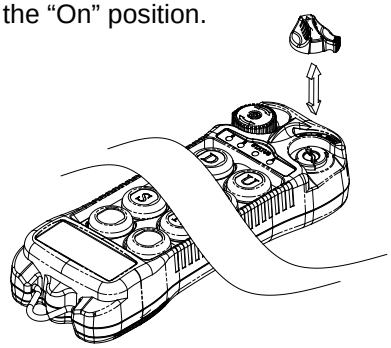


Figure 10

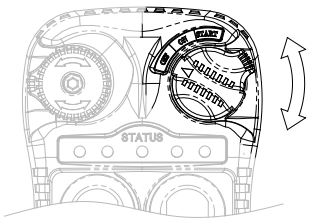


Figure 11

3. After turning on the controller power, check the Status LED on the controller handset for any sign of system irregularities (refer to “Status Light Indicators & Warnings” on page 22). If the system is normal the Status LED will light up green for two seconds, then slowly flash green.

4. If there are no signs of any system irregularities, then rotate the power key further clockwise to the “Start” position for up to two seconds. This will activate the E-Stop on the equipment. Thereafter, the same “Start” position will become an auxiliary function with momentary contact.

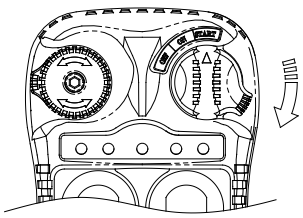


Figure 12

5. Now press any push button on the controller handset to operate the equipment. When a button is pressed, the Status LED will flash orange with a variable speed dependent on how far the button is pressed. The further a button is pressed, the faster the LED will flash. When no buttons are pressed, the Status LED will slowly blink green.

6. In case of an emergency, pressing down on the red emergency stop button will immediately disconnect the receiver E-Stop and turn off the unit. To reset the emergency stop button just rotate the red button either clockwise or counter-clockwise and then cycle power to the unit.

7. After a period of inactivity (push button not pressed) defined by the dip switch, the receiver E-Stop will be disconnected and the unit must cycle power before turning on again.

8. Turn off the controller power by rotating the power key counter-clockwise to the “Off” position (Status LED becomes a solid red for four seconds). This will disconnect the controller power and the receiver E-Stop altogether. Turn it further counter-clockwise to release the key.

7.2 STATUS LIGHT INDICATORS AND WARNINGS

Type	Display Type	Indication
1	Slow green blink (Normal Operation)	Controller on and in standby.
2	Blinking orange	Button has been pressed and the unit is transmitting. The speed at which the orange LED blinks is directly related to how far down the button is pressed.
3	1 red blink followed by a 2-second pause	Voltage goes below 1.9V during operation - Check power supply immediately.
4	2 red blinks followed by a 2-second pause	A push button is active while turning on the controller. The button that is active will be designated by the (25, 50, 75, 100) LEDs. See the following **Push Button Error** table.
5	3 red blinks followed by a 2-second pause	I-CHIP error.
6	Constant green for up to 2 seconds	Controller power on with no faults detected (prior to initiating the START function).
7	Solid Red	Stop command initiated with equipment ESTOP deactivated.
8	Solid Red	Voltage goes below 1.9V at initial power on - controller power shuts off.

7.3 PUSH BUTTON ERROR TABLE

25	50	75	100	Push Button
OFF	OFF	OFF	ON	1
OFF	OFF	ON	OFF	2
OFF	OFF	ON	ON	3
OFF	ON	OFF	OFF	4
OFF	ON	OFF	ON	5
OFF	ON	ON	OFF	6
OFF	ON	ON	ON	7
ON	OFF	OFF	OFF	8
ON	OFF	OFF	ON	9
ON	OFF	ON	OFF	10
ON	OFF	ON	ON	11
ON	ON	OFF	OFF	12

7.4 TROUBLESHOOTING TIPS

Problems	Possible Reasons	Suggestions
No response when controller push button is pressed (Improper startup & settings)	Controller low power	Check the CAN power supply.
	Emergency stop button activated prior to startup	Prior to turning on the controller power switch make sure that the red emergency stop button is elevated.
	Improper startup procedure	Redo the startup procedure by holding the power key at “START” position for up to 2.0 seconds and then release.
	Incorrect CAN ID	Make sure that the controller handset has the correct CAN ID.

8 DECLARATION OF CONFORMITY

MAGNETEK

EU Declaration of Conformity Certificate

For the following equipment:

Product	:	FlexPro Series Radio Remote Control
Product Receiver Models	:	CAN-2, MHR, WIC-2402, inteleSmart2, Flex M
Manufacturer's Name	:	Magnetek, Inc.
Manufacturer's Address	:	N49 W13650 Campbell Drive
		Menomonee Falls, WI 53051 USA

The undersigned hereby declares on behalf of Magnetek, that the above-referenced products, to which this declaration relates, is in conformity with the provisions of CE Mark Directive (93/68/EEC), Machinery Safety Directive (MD) 2006/42/EC, Radio Equipment Directive (RED, 2014/53/EU), EMC Directive (2014/30/EU), and the ROHS2 Directive (2011/65/EU).

The standards relevant for the evaluation of the product referenced above conformity to the directive requirements are as follows:

EN 301 489-1 v1.9.2:2011-09
EN 301 489-17 v2.1.1:2009-05
EN 300 220-1 v2.3.1:2010
EN 300 220-2 v2.3.1:2010
EN 60204-1:2006
EN 60204-32:2008

EN ISO 12100:2010
EN ISO 13849-1:2008
EN ISO 13849-2:2003
EN 13557:2003+A2:2008
EN 60529:1992

The European contact for Magnetek is:

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Bedford
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United Kingdom

Per Annex II.B of the Machinery Directive (2006/42/EC):

The machinery, product, assembly or sub-assembly covered by this Declaration of Conformity must not be put into service until the machinery into which it is to be incorporated has been declared in conformity with the provisions of the applicable Directive(s). This statement is only necessary where the product is to be incorporated into a machine or system (e.g. a safety component).

Signature of Authorized Person:

Travis Tedesco
Engineering Development Manager
Columbus McKinnon Corporation
Bridgeville, PA USA

Date of Issuance: 31 January 2019

Peter Stipan
Director of Development
Columbus McKinnon Corporation
Menomonee Falls, WI USA