



Flex 8EX and 12EX CE Systems

Radio Control Equipment Instruction Manual





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Service Information

Your New Radio System

Thank you for your purchase of Magnetek's Flex EX radio remote control system. Without a doubt, our Flex EX system is the ultimate solution for providing precise, undeterred, and safe control of your material.

If your product ever needs modification or service, please contact one of our representatives at the following locations:

U.S. Service Information

For questions regarding service or technical information contact: 1-866-MAG-SERV (1-866-624-7378)

International Service

262-783-3500

World Headquarters:

Magnetek, Inc. N49 W13650 Campbell Drive Menomonee Falls, WI 53051

Telephone: 800-288-8178 **Website:** www.magnetek.com

E-mail: mhcustomerservice@magnetek.com

Fax Numbers:

Main:800-298-3503Sales:262-783-3510Service:262-783-3508

Canada Service Information:

161 Orenda Road Unit 1 Brampton, Ontario L6W 1W3 Canada Phone: 800-792-7253

Fax: 905-828-5707

416-424-7617 (24/7 Service pager)

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1 Introduction

The Flex radio remote control systems are designed for control of industrial equipment and machinery such as overhead traveling cranes, jib cranes, gantry cranes, tower cranes, electric hoists, winches, monorails, conveyor belts, mining equipment and other material handling equipment where wireless control is preferred.

Each Flex system consists of a transmitter handset and receiver unit. Other standard-equipped accessories include transmitter waist belt, spare transmitter power key, clear vinyl pouch, "AA" alkaline batteries, compass direction decal sheet and user's manual.

List of notable features includes:

- **62 user-programmable channels** Advanced synthesized RF controls with 62 built-in channels; there are no more fixed channels and fragile quartz crystals to break.
- Automatic channel scanning receiver No more hassle of climbing up the crane to change receiver channels.
- Over 1 million unique ID codes (20-bit) Every Flex system has its own unique ID codes and serial number; no repeats.
- Advanced controls The Flex system utilizes advanced microprocessor controls with 32-bit CRC and Hamming Code, which provide ultra-fast, safe, precise, and error-free encoding and decoding.
- **Unique I-CHIP design** The I-CHIP functions in a way that is very similar to SIM cards used on mobile phones, with the ability to transfer system information and settings from one transmitter to another without the hassle of resetting the spares.
- **Reliable pushbuttons** The in-house-designed pushbuttons with gold-plated contacts are rated for more than 1 million press cycles.
- **Low power consumption** Requires only two "AA" alkaline batteries for more than 100 hours of operating time between replacements.
- **Ultra-durable nylon and fiberglass composite enclosures** Highly resistant to breakage and deformation, even in the most abusive environments.
- **Full compliance** All systems fully comply with the FCC Part-15 Rules, European Directives (Safety, EMC, RED, and Machinery), and Industry Canada Specifications (IC).

1.1 Product Manual Safety Information

Magnetek, Inc. (Magnetek) offers a broad range of radio remote control products, control products and adjustable frequency drives, and industrial braking systems for material handling applications. This manual has been prepared by Magnetek to provide information and recommendations for the installation, use, operation and service of Magnetek's material handling products and systems (Magnetek Products). Anyone who uses, operates, maintains, services, installs or owns Magnetek Products should know, understand, and follow the instructions and safety recommendations in this manual for Magnetek Products.

The recommendations in this manual do not take precedence over any of the following requirements relating to cranes, hoists lifting devices or other material handling equipment which use or include Magnetek Products:

- Instructions, manuals, and safety warnings of the manufacturers of the equipment where the radio system is used,
- Plant safety rules and procedures of the employers and the owners of facilities where the Magnetek Products are being used,
- Regulations issued by the Occupational Health and Safety Administration (OSHA),
- Applicable local, state or federal codes, ordinances, standards and requirements, or
- Safety standards and practices for the industries in which Magnetek Products are used.

This manual does not include or address the specific instructions and safety warnings of these manufacturers or any of the other requirements listed above. It is the responsibility of the owners, users and operators of the Magnetek Products to know, understand and follow all of these requirements. It is the responsibility of the employer to make its employees aware of all of the above listed requirements and to make certain that all operators are properly trained. No one should use Magnetek Products prior to becoming familiar with and being trained in these requirements and the instructions and safety recommendations in this manual.

WARRANTY INFORMATION

For information on Magnetek's product warranties by product type, please visit www.magnetek.com.

1.2 Warnings and Cautions

Throughout this document WARNING and CAUTION statements have been deliberately placed to highlight items critical to the protection of personnel and equipment.



WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.



CAUTION indicates a potentially hazardous situation which, if not avoided, could result in minor or moderate injury. It may also be used to alert against unsafe practices.

NOTE: A NOTE statement is used to notify people of installation, operation, programming, or maintenance information that is important, but not hazard-related.

WARNINGS and CAUTIONS SHOULD NEVER BE DISREGARDED.

The safety rules in this section are not intended to replace any rules or regulations of any applicable local, state, or federal governing organizations. Always follow your local lockout and tagout procedure when maintaining any radio equipment. The following information is intended to be used in conjunction with other rules or regulations already in existence. It is important to read all of the safety information contained in this section before installing or operating the Radio Control System.

2 Critical Installation Considerations



Prior to installation and operation of this equipment, read and develop an understanding of the contents of this manual and the operation manual of the equipment or device to which this equipment will be interfaced. Failure to follow this warning could result in serious injury or death and damage to equipment.

All equipment must have a mainline contactor installed and all tracked cranes, hoists, lifting devices and similar equipment must have a brake installed. Failure to follow this warning could result in serious injury or death and damage to equipment.

An audible and/or visual warning means must be provided on all remote-controlled equipment as required by code, regulation, or industry standard. These audible and/or visual warning devices must meet all governmental requirements. Failure to follow this warning could result in serious injury or death and damage to equipment.

Follow your local lockout/tagout procedure before maintaining any remote-controlled equipment. Always remove all electrical power from the crane, hoist, lifting device or similar equipment before attempting any installation procedures. De-energize and tagout all sources of electrical power before touch-testing any equipment. Failure to follow this warning could result in serious injury or death and damage to equipment.

The direct outputs of this product are not designed to interface directly to two state safety critical maintained functions, i.e., magnets, vacuum lifts, pumps, emergency equipment, etc. A mechanically locking intermediate relay system with separate power considerations must be provided. Failure to follow this warning could result in serious injury or death or damage to equipment.

2.1 General

Radio-controlled material handling equipment operates in several directions. Cranes, hoists, lifting devices and other material handling equipment can be large, and can operate at high speeds. The equipment is often operated in areas where people are working in close proximity to the material handling equipment. **The operator must exercise extreme caution at all times.** Workers must constantly be alert to avoid accidents. The following recommendations have been included to indicate how careful and thoughtful actions may prevent injuries, prevent damage to equipment, or even save a life.

2.2 Persons Authorized to Operate Radio-Controlled Cranes

Only properly trained persons designated by management should be permitted to operate radio-controlled equipment.

Radio-controlled cranes, hoists, lifting devices and other material handling equipment should not be operated by any person who cannot read or understand signs, notices and operating instructions that pertain to the equipment.

Radio-controlled equipment should not be operated by any person with insufficient eyesight or hearing or by any person who may be suffering from a disorder or illness that may cause them to lose control of the equipment, is taking any medication that may cause loss of equipment control, or is under the influence of alcohol or drugs.

2.3 Safety Information and Recommended Training for Radio-Controlled Equipment Operators

Anyone being trained to operate radio-controlled equipment should possess as a minimum the following knowledge and skills before using the radio-controlled equipment.

The operator should:

- have knowledge of hazards pertaining to equipment operation
- · have knowledge of safety rules for radio-controlled equipment
- have the ability to judge distance of moving objects
- know how to properly test prior to operation
- be trained in the safe operation of the radio transmitter as it pertains to the crane, hoist, lifting device or other material handling equipment being operated
- have knowledge of the use of equipment warning lights and alarms
- have knowledge of the proper storage space for a radio control transmitter when not in use
- be trained in transferring a radio control transmitter to another person
- · be trained how and when to report unsafe or unusual operating conditions
- test the transmitter emergency stop and all warning devices prior to operation; testing should be done on each shift, without a load
- be thoroughly trained and knowledgeable in proper and safe operation of the crane, hoist, lifting device, or other material handling equipment that utilizes the radio control
- know how to keep the operator and other people clear of lifted loads and to avoid "pinch" points
- continuously watch and monitor status of lifted loads
- know and follow cable and hook inspection procedures
- know and follow the local lockout and tagout procedures when servicing radio-controlled equipment
- know and follow all applicable operating and maintenance manuals, safety procedures, regulatory requirements, and industry standards and codes

The operator shall not:

- lift or move more than the rated load
- operate the material handling equipment if the direction of travel or function engaged does not agree with what is indicated on the controller
- use the crane, hoist or lifting device to lift, support or transport people
- lift or carry any loads over people
- operate the crane, hoist or lifting device unless all persons, including the operator, are and remain clear of the supported load and any potential pinch points
- operate a crane, hoist or lifting device when the device is not centered over the load

- operate a crane, hoist or lifting device if the chain or wire rope is not seated properly in the sprockets, drum or sheave
- operate any damaged or malfunctioning crane, hoist, lifting device or other material handling equipment
- · change any settings or controls without authorization and proper training
- · remove or obscure any warning or safety labels or tags
- leave any load unattended while lifted
- leave power on the radio-controlled equipment when the equipment is not in operation
- operate any material handling equipment using a damaged controller because the unit may be unsafe
- operate manual motions with other than manual power
- operate radio-controlled equipment when low battery indicator is on



The operator should not attempt to repair any radio controller. If any product performance or safety concerns are observed, the equipment should immediately be taken out of service and be reported to the supervisor. Damaged and inoperable radio controller equipment should be returned to Magnetek for evaluation and repair. Failure to follow this warning could result in serious injury or death and damage to equipment.

2.4 Transmitter Unit

Transmitter switches should never be mechanically blocked on or off. When not in use, the operator should turn the transmitter off. A secure storage space should be provided for the transmitter unit, and the transmitter unit should always be placed there when not in use. This precaution will help prevent unauthorized people from operating the material handling equipment.

Spare transmitters should be stored in a secure storage space and only removed from the storage space after the current transmitter in use has been turned off, taken out of the service area and secured.

2.5 Pre-Operation Test

At the start of each work shift, or when a new operator takes control of the crane, operators should do, as a minimum, the following steps before making lifts with any crane or hoist:

Test all warning devices.

Test all direction and speed controls.

Test the transmitter emergency stop.

2.6 Batteries



Know and follow proper battery handling, charging and disposal procedures. Improper battery procedures can cause batteries to explode or do other serious damage. Failure to follow this warning could result in serious injury or death and damage to equipment.

2.7 Battery Handling

Use only batteries approved by Magnetek for the specific product.

Do not dispose of a battery pack in fire; it may explode.

Do not attempt to open the battery pack.

Do not short-circuit the battery.

For intrinsically safe environments, only use specified Magnetek intrinsically safe batteries.

Keep the battery pack environment cool during charging operation and storage (i.e., not in direct sunlight or close to a heating source).

2.8 Battery Charging

For those transmitters equipped with battery chargers, please familiarize all users with the instructions of the charger before attempting to use.

Do not attempt to charge non-rechargeable battery packs.

Avoid charging partially discharged rechargeable batteries to help prolong battery cycle life.

Avoid charging the battery pack for more than 24 hours at a time.

Do not charge batteries in a hazardous environment.

Do not short the charger.

Do not attempt to charge a damaged battery.

Use only Magnetek-approved chargers for the appropriate battery pack.

Do not attempt to use a battery that is leaking, swollen or corroded.

Charger units are not intended for outdoor use. Use only indoors.

2.9 Battery Disposal

Before disposing of batteries, consult local and governmental regulatory requirements for proper disposal procedure.

2.10 Specific System Warnings

Below are some specific operating safety tips that should be strictly followed when operating a Flex EX system:

- Check the Status LED on the transmitter for any signs of low battery power (see Section 7.2 on page 62).
- Check the Status LED on the transmitter for any signs of irregularities (see Section 7.2 on page 62).
- Make sure the system is not set to the same channel as any other Flex systems in use within a
 distance of 300 meters (900 feet).
- Never operate a crane or equipment with two transmitter handsets at the same time unless they
 are programmed to do so.

3 General System Information

3.1 Transmitter

3.1.1 External Illustration

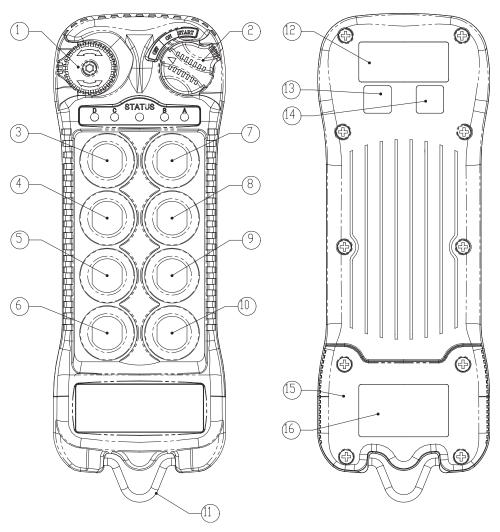


Fig. 1: Flex 8EX

1.	Emergency Stop Button	9.	Pushbutton #5
2.	Removable Power Key Switch	10.	Pushbutton #7
3.	Pushbutton #2	11.	Strap Ring
4.	Pushbutton #4	12.	System Information
5.	Pushbutton #6	13.	System Channel
6.	Pushbutton #8	14.	Crane Number
7.	Pushbutton #1	15.	Battery Cover
8.	Pushbutton #3	16.	FCC Information

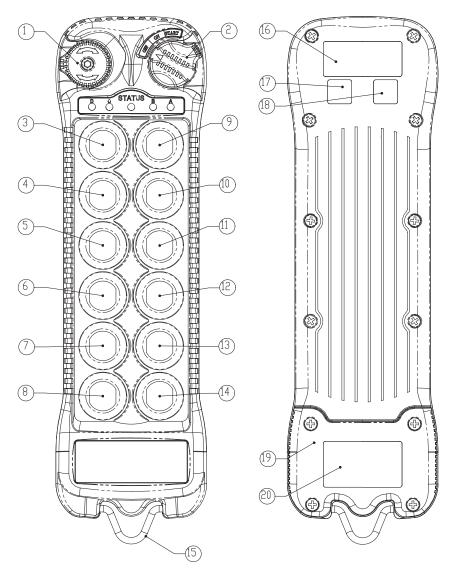


Fig. 2: Flex 12EX

1.	Emergency Stop Button	11.	Pushbutton #5
2.	Removable Power Key Switch	12.	Pushbutton #7
3.	Pushbutton #2	13.	Pushbutton #9
4.	Pushbutton #4	14.	Pushbutton #11
5.	Pushbutton #6	15.	Strap Ring
6.	Pushbutton #8	16.	System Information
7.	Pushbutton #10	17.	System Channel
8.	Pushbutton #12	18.	Crane Number
9.	Pushbutton #1	19.	Battery Cover
10.	Pushbutton #3	20.	FCC Information

3.1.2 Internal Illustration

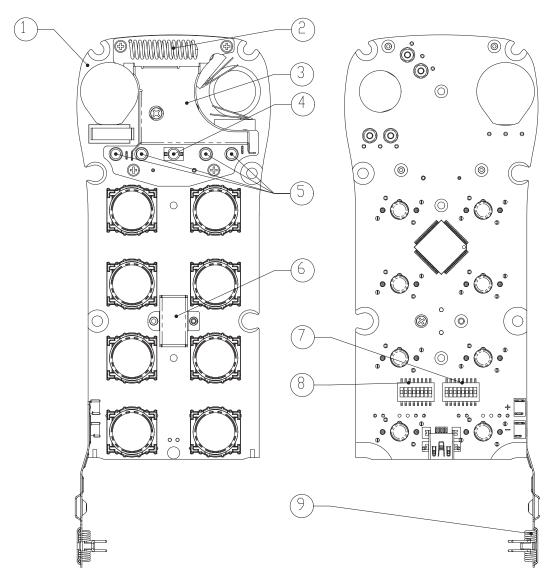


Fig. 3: Flex 8EX

- 1. Encoder Board
- 2. Aerial Antenna
- 3. Transmitting Module
- 4. Status LED Display
- 5. Function LED Displays
- 6. I-CHIP
- 7. Function Dipswitch
- 8. Channel Dipswitch
- 9. Battery Contact Mechanism

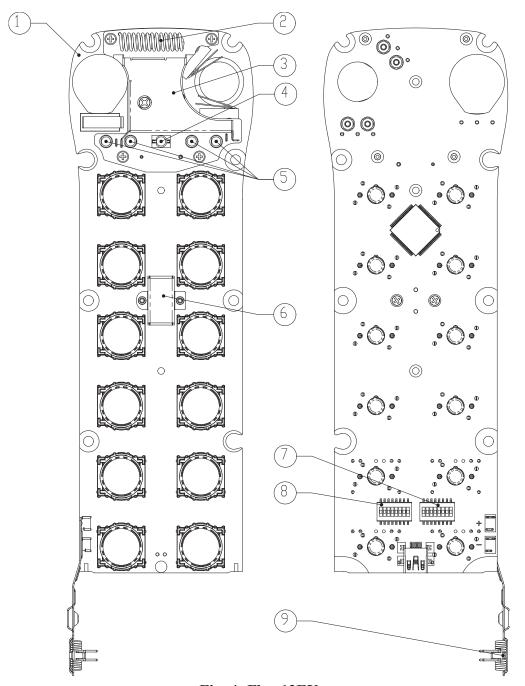


Fig. 4: Flex 12EX

- 1. Encoder Board
- 2. Aerial Antenna
- 3. Transmitting Module
- 4. Status LED Display
- 5. Function LED Displays
- 6. I-CHIP
- 7. Function Dipswitch
- 8. Channel Dipswitch
- 9. Battery Contact Mechanism

3.2 Transmitter Handset (A/B)

3.2.1 External Illustration

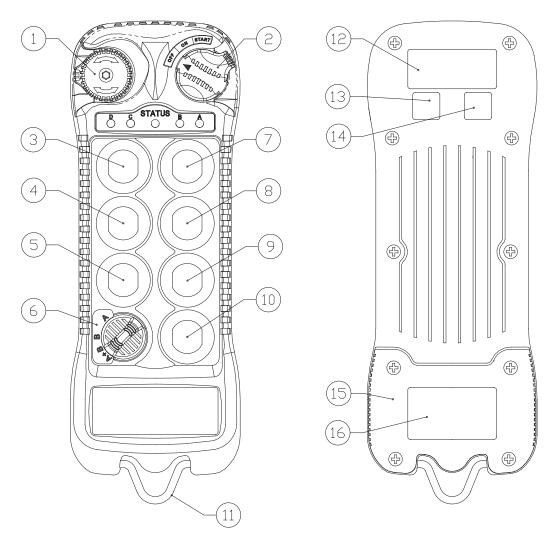


Fig. 5: Flex 8EX

1.	Emergency Stop Button	9.	Pushbutton #5
2.	Removable Power Key Switch	10.	Pushbutton #7
3.	Pushbutton #2	11.	Strap Ring
4.	Pushbutton #4	12.	System Information
5.	Pushbutton #6	13.	System Channel
6.	Select A, B, A+B Rotary Switch	14.	Crane Number
7.	Pushbutton #1	15.	Battery Cover
8.	Pushbutton #3	16.	FCC Information

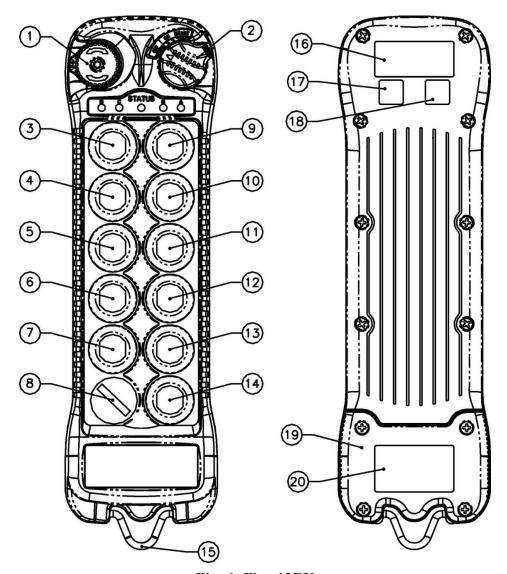


Fig. 6: Flex 12EX

1.	Emergency Stop Button	11.	Pushbutton #5
2.	Removable Power Key Switch	12.	Pushbutton #7
3.	Pushbutton #2	13.	Pushbutton #9
4.	Pushbutton #4	14.	Pushbutton #11
5.	Pushbutton #6	15.	Strap Ring
6.	Pushbutton #8	16.	System Information
7.	Pushbutton #10	17.	System Channel
8.	Select A, B, A+B Rotary Switch	18.	Crane Number
9.	Pushbutton #1	19.	Battery Cover
10.	Pushbutton #3	20.	FCC Information

3.2.2 Internal Illustration

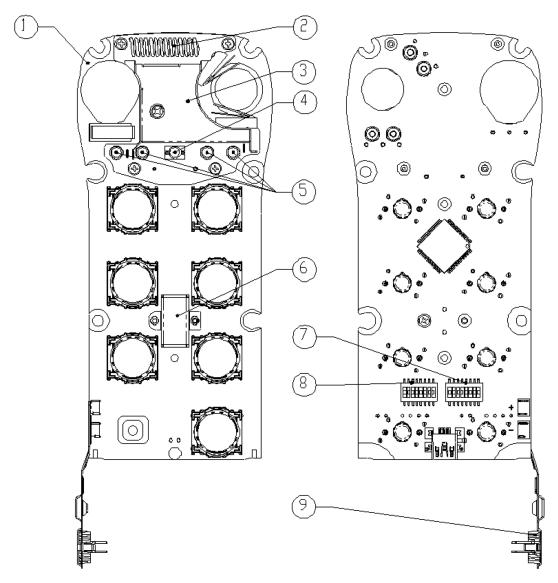


Fig. 7: Flex 8EX

- 1. Encoder Board
- 2. Aerial Antenna
- 3. Transmitting Module
- 4. Status LED Display
- 5. Function LED Displays
- 6. I-CHIP
- 7. Function Dipswitch
- 8. Channel Dipswitch
- 9. Battery Contact Mechanism

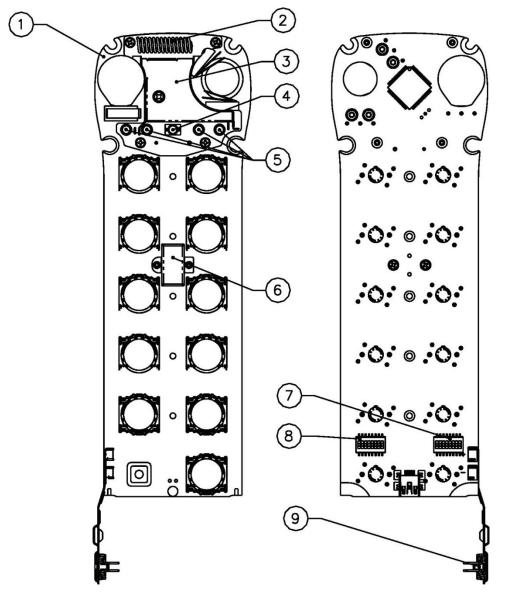


Fig. 8: Flex 12EX

- 1. Encoder Board
- 2. Aerial Antenna
- 3. Transmitting Module
- 4. Status LED Display
- 5. Function LED Displays
- 6. I-CHIP
- 7. Function Dipswitch
- 8. Channel Dipswitch
- 9. Battery Contact Mechanism

3.3 Receiver Unit

3.3.1 External Illustration

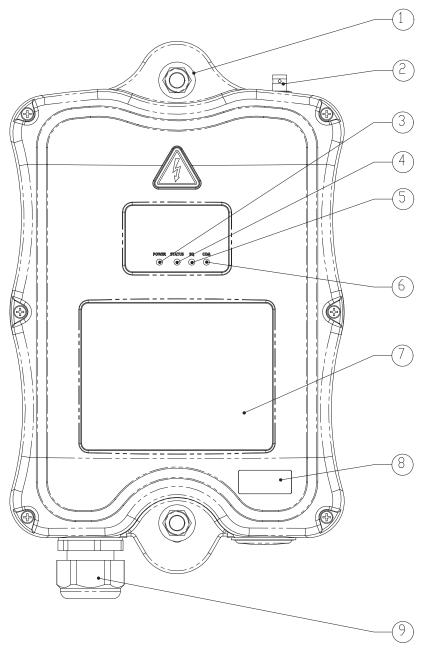


Fig. 9

1.	Shock Mount	6.	COM LED Display
2.	Optional External Antenna Jack	7.	Output Contact Diagram
3.	Power LED Display	8.	System Information
4.	Status LED Display	9.	Cord Grip
5.	SQ LED Display		

3.3.2 Internal Illustration

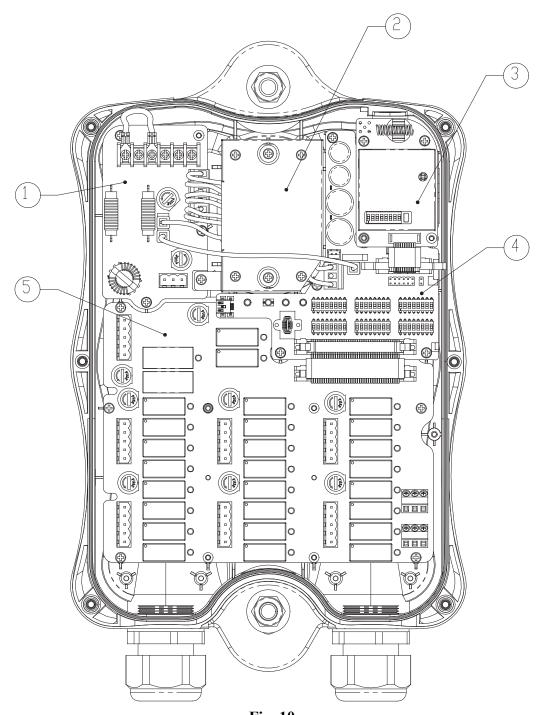


Fig. 10

- 1. AC Line Filter
- 2. Power Transformer
- 3. Receiving Module
- 4. Decoder Module
- 5. Output Relay Board

4 Function Settings

4.1 Transmitter Handset

4.1.1 System Channel Settings

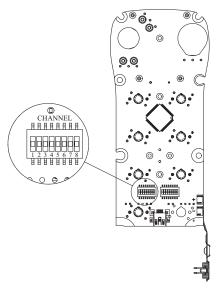


Fig. 11

Set the transmitter channel by adjusting the channel dipswitch located on the backside of the transmitter encoder board (see Fig. 11). Only the first six (6) positions are used for channel programming (see Fig. 12). The system channels table in Section 5 on page 52 illustrates which dipswitch setting corresponds to which channel. Once the transmitter channel is altered, be sure to change the receiver channel as well. The channel on both the transmitter and the receiver must be identical in order for the system to work. To change the receiver channel, see Section 4.2.1 on page 40.

Example:

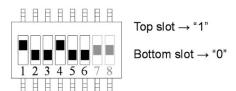
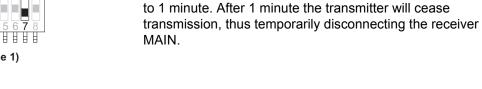


Fig. 12

The above dipswitch setting "1 0 0 1 0 0" corresponds to "channel 36" in the system channels table in **Section 5 on page 52**.

4.1.2 Continuous Transmitting Time Adjustment







After the pushbutton is released, the transmitter will continue to transmit neutral signals to the receiver depending on the time set in the I-CHIP. The default time is 3 minutes. After that time the transmitter will cease transmission, thus temporarily disconnecting the receiver MAIN. Please contact your local dealer if your application requires transmitting on time other than the default value above.

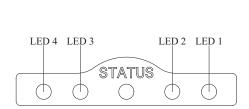
After the pushbutton is released, the transmitter will

continue to transmit neutral signals to the receiver for up

4.1.3 Pushbutton Functions with LED Displays

4.1.3.1 Standard Pushbutton Configuration (Transmitter Toggle)

Set transmitter toggle (latching output relay) function by adjusting the 8-position function dipswitch located on the backside of the transmitter encoder board (**see Fig. 13**). LED 1 through LED 4 shown inside the shaded boxes in the table below illustrate which LED on the transmitter will illuminate when the designated pushbutton is pressed (PB5 - PB8 for 8EX; PB7 - PB12 for 12EX).



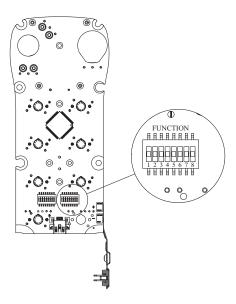


Fig. 13

For 8EX:

	DIP	PB5	PB6	PB7	PB8*
1	00000000	Normal	Normal	Normal	Normal
2	00000101	Normal	Normal	Normal	LED 4
3	00000110	Normal	Normal	LED 3	LED 4
4	00000111	Normal	LED 2	LED 3	LED 4
5	00001000	LED 1	LED 2	LED 3	LED 4

NOTE: *PB8 is not available on the A/B transmitters

 $PB5...PB8 \rightarrow Pushbutton\ number$ $Normal \rightarrow Normal\ momentary\ contact$ $LED\ 1...LED\ 4 \rightarrow Transmitter\ toggled\ with\ designated\ LED\ Display$

For 12EX:

	DIP	PB7	PB8	PB9	PB10	PB11	PB12*
1	00000000	Normal	Normal	Normal	Normal	Normal	Normal
2	00001001	Normal	Normal	Normal	LED 4	Normal	Normal
3	00001010	Normal	Normal	LED 3	LED 4	Normal	Normal
4	00001011	Normal	LED 2	LED 3	LED 4	Normal	Normal
5	00001100	LED 1	LED 2	LED 3	LED 4	Normal	Normal
6	00001101	Normal	Normal	Normal	Normal	Normal	LED 4
7	00001110	Normal	Normal	Normal	Normal	LED 3	LED 4
8	00001111	Normal	Normal	Normal	LED 2	LED 3	LED 4
9	00010000	Normal	Normal	LED 1	LED 2	LED 3	LED 4

NOTE: *PB12 is not available on the A/B transmitters

 $PB7...PB12 \rightarrow Pushbutton\ number$ $Normal \rightarrow Normal\ momentary\ contact$ $LED\ 1...LED\ 4 \rightarrow Transmitter\ toggled\ with\ designated\ LED\ Display$

4.1.3.2 Standard Pushbutton Configuration (A/B Selector)

There are four (4) different types of A/B selector sequences available on the Flex system. Choose the one that is most suitable for your application.

Type-A selector sequence: $A+B \rightarrow A \rightarrow B \rightarrow A+B...$

Type-B selector sequence: Off \rightarrow A \rightarrow B \rightarrow Off \rightarrow A \rightarrow B...

Type-C selector sequence: $A \rightarrow B \rightarrow A+B \rightarrow A \rightarrow B \rightarrow A+B...$

Type-D selector sequence: Off \rightarrow A \rightarrow B \rightarrow A+B \rightarrow Off \rightarrow A \rightarrow B \rightarrow A+B...

For 8EX:

	DIP	PB5	PB6	РВ7	PB8*
6	00101111	Normal	Normal	A/1&2	Normal
7	00110000	Normal	Normal	B/1&2	Normal
8	00110001	Normal	Normal	C/1&2	Normal
9	00110010	Normal	Normal	D/1&2	Normal
10	00110011	Normal	Normal	Normal	A/3&4
11	00110100	Normal	Normal	Normal	B/3&4
12	00110101	Normal	Normal	Normal	C/3&4
13	00110110	Normal	Normal	Normal	D/3&4
14	00110111	Normal	Normal	A/1&2	A/3&4
15	00111000	Normal	Normal	A/1&2	B/3&4
16	00111001	Normal	Normal	A/1&2	C/3&4
17	00111010	Normal	Normal	A/1&2	D/3&4
18	00111011	Normal	Normal	B/1&2	B/3&4
19	00111100	Normal	Normal	B/1&2	C/3&4
20	00111101	Normal	Normal	B/1&2	D/3&4
21	00111110	Normal	Normal	C/1&2	C/3&4
22	00111111	Normal	Normal	C/1&2	D/3&4
23	01000000	Normal	Normal	D/1&2	D/3&4

NOTE: *PB8 is not available on the A/B transmitters

PB5…PB8 → Pushbutton number

Normal o Normal momentary contact

For 12EX:

	DIP	PB7	PB8	PB9	PB10	PB11	PB12*
10	00101111	A/1&2	Normal	Normal	Normal	Normal	Normal
11	00110000	B/1&2	Normal	Normal	Normal	Normal	Normal
12	00110001	C/1&2	Normal	Normal	Normal	Normal	Normal
13	00110010	D/1&2	Normal	Normal	Normal	Normal	Normal
14	00110011	Normal	A/3&4	Normal	Normal	Normal	Normal
15	00110100	Normal	B/3&4	Normal	Normal	Normal	Normal
16	00110101	Normal	C/3&4	Normal	Normal	Normal	Normal
17	00110110	Normal	D/3&4	Normal	Normal	Normal	Normal
18	00110111	A/1&2	A/3&4	Normal	Normal	Normal	Normal
19	00111000	A/1&2	B/3&4	Normal	Normal	Normal	Normal
20	00111001	A/1&2	C/3&4	Normal	Normal	Normal	Normal
21	00111010	A/1&2	D/3&4	Normal	Normal	Normal	Normal
22	00111011	B/1&2	B/3&4	Normal	Normal	Normal	Normal
23	00111100	B/1&2	C/3&4	Normal	Normal	Normal	Normal
24	00111101	B/1&2	D/3&4	Normal	Normal	Normal	Normal
25	00111110	C/1&2	C/3&4	Normal	Normal	Normal	Normal
26	00111111	C/1&2	D/3&4	Normal	Normal	Normal	Normal
27	01000000	D/1&2	D/3&4	Normal	Normal	Normal	Normal

NOTE: *PB12 is not available on the A/B transmitters

 $PB7...PB12 \rightarrow Pushbutton number$ Normal \rightarrow Normal momentary contact

	DIP	PB7	PB8	PB9	PB10	PB11	PB12*
28	01000001	Normal	Normal	A/1&2	Normal	Normal	Normal
29	01000010	Normal	Normal	B/1&2	Normal	Normal	Normal
30	01000011	Normal	Normal	C/1&2	Normal	Normal	Normal
31	01000100	Normal	Normal	D/1&2	Normal	Normal	Normal
32	01000101	Normal	Normal	Normal	A/3&4	Normal	Normal
33	01000110	Normal	Normal	Normal	B/3&4	Normal	Normal
34	01000111	Normal	Normal	Normal	C/3&4	Normal	Normal
35	01001000	Normal	Normal	Normal	D/3&4	Normal	Normal
36	01001001	Normal	Normal	A/1&2	A/3&4	Normal	Normal
37	01001010	Normal	Normal	A/1&2	B/3&4	Normal	Normal
38	01001011	Normal	Normal	A/1&2	C/3&4	Normal	Normal
39	01001100	Normal	Normal	A/1&2	D/3&4	Normal	Normal
40	01001101	Normal	Normal	B/1&2	B/3&4	Normal	Normal
41	01001110	Normal	Normal	B/1&2	C/3&4	Normal	Normal
42	01001111	Normal	Normal	B/1&2	D/3&4	Normal	Normal
43	01010000	Normal	Normal	C/1&2	C/3&4	Normal	Normal
44	01010001	Normal	Normal	C/1&2	D/3&4	Normal	Normal
45	01010010	Normal	Normal	D/1&2	D/3&4	Normal	Normal

NOTE: *PB12 is not available on the A/B transmitters

 $PB7...PB12 \rightarrow Pushbutton number$ Normal \rightarrow Normal momentary contact

	DIP	PB7	PB8	PB9	PB10	PB11	PB12*
46	01010011	Normal	Normal	Normal	Normal	A/1&2	Normal
47	01010100	Normal	Normal	Normal	Normal	B/1&2	Normal
48	01010101	Normal	Normal	Normal	Normal	C/1&2	Normal
49	01010110	Normal	Normal	Normal	Normal	D/1&2	Normal
50	01010111	Normal	Normal	Normal	Normal	Normal	A/3&4
51	01011000	Normal	Normal	Normal	Normal	Normal	B/3&4
52	01011001	Normal	Normal	Normal	Normal	Normal	C/3&4
53	01011010	Normal	Normal	Normal	Normal	Normal	D/3&4
54	01011011	Normal	Normal	Normal	Normal	A/1&2	A/3&4
55	01011100	Normal	Normal	Normal	Normal	A/1&2	B/3&4
56	01011101	Normal	Normal	Normal	Normal	A/1&2	C/3&4
57	01011110	Normal	Normal	Normal	Normal	A/1&2	D/3&4
58	01011111	Normal	Normal	Normal	Normal	B/1&2	B/3&4
59	01100000	Normal	Normal	Normal	Normal	B/1&2	C/3&4
60	01100001	Normal	Normal	Normal	Normal	B/1&2	D/3&4
61	01100010	Normal	Normal	Normal	Normal	C/1&2	C/3&4
62	01100011	Normal	Normal	Normal	Normal	C/1&2	D/3&4
63	01100100	Normal	Normal	Normal	Normal	D/1&2	D/3&4

NOTE: *PB12 is not available on the A/B transmitters

 $PB7...PB12 \rightarrow Pushbutton number$ Normal \rightarrow Normal momentary contact

4.1.3.3 Inline Pushbutton Configuration (Transmitter Toggle)

The pushbutton arrangement for inline pushbutton setup starts from top to bottom and then from the right column to the left column (see Fig. 14 and Fig. 15). To set the inline pushbutton configuration, see JP4 and JP5 jumper settings in Section 4.2.5 on page 48. With inline pushbutton configuration, PB1 and PB2 still correspond to output relay K1 - K4; PB3 and PB4 correspond to relay K5 - K8, etc.

For 8EX:

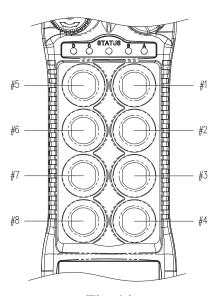


Fig. 14

	DIP	PB5	PB6	PB7	PB8*
24	00000000	Normal	Normal	Normal	Normal
25	00000101	Normal	Normal	Normal	LED 4
26	00010100	Normal	Normal	LED 3	LED 4
27	00010101	Normal	LED 2	LED 3	LED 4
28	00010110	LED 1	LED 2	LED 3	LED 4

NOTE: *PB8 is not available on the A/B transmitters

 $\textit{PB5}...\textit{PB8} \rightarrow \textit{Pushbutton number}$

 $\textit{Normal} \rightarrow \textit{Normal momentary contact}$

LED 1...LED 4 \rightarrow Transmitter toggled with designated LED Display

For 12EX:

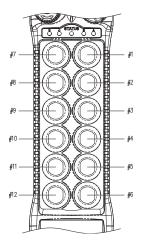


Fig. 15

	DIP	PB7	PB8	PB9	PB10	PB11	PB12*
64	00000000	Normal	Normal	Normal	Normal	Normal	Normal
65	00000101	Normal	Normal	Normal	LED 4	Normal	Normal
66	00010100	Normal	Normal	LED 3	LED 4	Normal	Normal
67	00010101	Normal	LED 2	LED 3	LED 4	Normal	Normal
68	00010110	LED 1	LED 2	LED 3	LED 4	Normal	Normal
69	00001001	Normal	Normal	Normal	Normal	LED 4	Normal
70	00010111	Normal	Normal	Normal	LED 3	LED 4	Normal
71	00011000	Normal	Normal	LED 2	LED 3	LED 4	Normal
72	00011001	Normal	LED 1	LED 2	LED 3	LED 4	Normal
73	00001101	Normal	Normal	Normal	Normal	Normal	LED 4
74	00011010	Normal	Normal	Normal	Normal	LED 3	LED 4
75	00011011	Normal	Normal	Normal	LED 2	LED 3	LED 4
76	00011100	Normal	Normal	LED 1	LED 2	LED 3	LED 4

NOTE: *PB12 is not available on the A/B transmitters

 $\textit{PB7}...\textit{PB12} \rightarrow \textit{Pushbutton number}$

Normal o Normal momentary contact

LED 1...LED 4 \rightarrow Transmitter toggled with designated LED Display

4.1.3.4 Inline Pushbutton Configuration (A/B Selector)

There are four (4) different types of A/B selector sequences available on the Flex system. Choose the one that is most suitable for your application.

Type-A selector sequence: $A+B \rightarrow A \rightarrow B \rightarrow A+B...$

Type-B selector sequence: Off \rightarrow A \rightarrow B \rightarrow Off \rightarrow A \rightarrow B...

Type-C selector sequence: $A \rightarrow B \rightarrow A+B \rightarrow A \rightarrow B \rightarrow A+B...$

Type-D selector sequence: Off \rightarrow A \rightarrow B \rightarrow A+B \rightarrow Off \rightarrow A \rightarrow B \rightarrow A+B...

For 8EX:

	DIP	PB5	PB6	РВ7	PB8*
29	01110011	Normal	Normal	A/1&2	Normal
30	01110100	Normal	Normal	B/1&2	Normal
31	01110101	Normal	Normal	C/1&2	Normal
32	01110110	Normal	Normal	D/1&2	Normal
33	00110011	Normal	Normal	Normal	A/3&4
34	00110100	Normal	Normal	Normal	B/3&4
35	00110101	Normal	Normal	Normal	C/3&4
36	00110110	Normal	Normal	Normal	D/3&4
37	01110111	Normal	Normal	A/1&2	A/3&4
38	01111000	Normal	Normal	A/1&2	B/3&4
39	01111001	Normal	Normal	A/1&2	C/3&4
40	01111010	Normal	Normal	A/1&2	D/3&4
41	01111011	Normal	Normal	B/1&2	B/3&4
42	01111100	Normal	Normal	B/1&2	C/3&4
43	01111101	Normal	Normal	B/1&2	D/3&4
44	01111110	Normal	Normal	C/1&2	C/3&4
45	01111111	Normal	Normal	C/1&2	D/3&4
46	10000000	Normal	Normal	D/1&2	D/3&4

NOTE: *PB8 is not available on the A/B transmitters

 $PB5...PB8 \rightarrow Pushbutton number$

Normal → Normal momentary contact

For 12EX:

	DIP	PB9	PB10	PB11	PB12*
77	01110011	A/1&2	Normal	Normal	Normal
78	01110100	B/1&2	Normal	Normal	Normal
79	01110101	C/1&2	Normal	Normal	Normal
80	01110110	D/1&2	Normal	Normal	Normal
81	00110011	Normal	A/3&4	Normal	Normal
82	00110100	Normal	B/3&4	Normal	Normal
83	00110101	Normal	C/3&4	Normal	Normal
84	00110110	Normal	D/3&4	Normal	Normal
85	01110111	A/1&2	A/3&4	Normal	Normal
86	01111000	A/1&2	B/3&4	Normal	Normal
87	01111001	A/1&2	C/3&4	Normal	Normal
88	01111010	A/1&2	D/3&4	Normal	Normal
89	01111011	B/1&2	B/3&4	Normal	Normal
90	01111100	B/1&2	C/3&4	Normal	Normal
91	01111101	B/1&2	D/3&4	Normal	Normal
92	01111110	C/1&2	C/3&4	Normal	Normal
93	01111111	C/1&2	D/3&4	Normal	Normal
94	1000000	D/1&2	D/3&4	Normal	Normal

NOTE: *PB12 is not available on the A/B transmitters

 $PB7...PB12 \rightarrow Pushbutton\ number$ Normal \rightarrow Normal momentary contact

	DIP	PB9	PB10	PB11	PB12*
95	10000001	Normal	A/1&2	Normal	Normal
96	10000010	Normal	B/1&2	Normal	Normal
97	10000011	Normal	C/1&2	Normal	Normal
98	10000100	Normal	D/1&2	Normal	Normal
99	01000101	Normal	Normal	A/3&4	Normal
100	01000110	Normal	Normal	B/3&4	Normal
101	01000111	Normal	Normal	C/3&4	Normal
102	01001000	Normal	Normal	D/3&4	Normal
103	10000101	Normal	A/1&2	A/3&4	Normal
104	10000110	Normal	A/1&2	B/3&4	Normal
105	10000111	Normal	A/1&2	C/3&4	Normal
106	10001000	Normal	A/1&2	D/3&4	Normal
107	10001001	Normal	B/1&2	B/3&4	Normal
108	10001010	Normal	B/1&2	C/3&4	Normal
109	10001011	Normal	B/1&2	D/3&4	Normal
110	10001100	Normal	C/1&2	C/3&4	Normal
111	10001101	Normal	C/1&2	D/3&4	Normal
112	10001110	Normal	D/1&2	D/3&4	Normal

NOTE: *PB12 is not available on the A/B transmitters

 $PB7...PB12 \rightarrow Pushbutton\ number$ Normal \rightarrow Normal momentary contact

	DIP	PB9	PB10	PB11	PB12*
113	10001111	Normal	Normal	A/1&2	Normal
114	10010000	Normal	Normal	B/1&2	Normal
115	10010001	Normal	Normal	C/1&2	Normal
116	10010010	Normal	Normal	D/1&2	Normal
117	01010111	Normal	Normal	Normal	A/3&4
118	01011000	Normal	Normal	Normal	B/3&4
119	01011001	Normal	Normal	Normal	C/3&4
120	01011010	Normal	Normal	Normal	D/3&4
121	10010011	Normal	Normal	A/1&2	A/3&4
122	10010100	Normal	Normal	A/1&2	B/3&4
123	10010101	Normal	Normal	A/1&2	C/3&4
124	10010110	Normal	Normal	A/1&2	D/3&4
125	10010111	Normal	Normal	B/1&2	B/3&4
126	10011000	Normal	Normal	B/1&2	C/3&4
127	10011001	Normal	Normal	B/1&2	D/3&4
128	10011010	Normal	Normal	C/1&2	C/3&4
129	10011011	Normal	Normal	C/1&2	D/3&4
130	10011100	Normal	Normal	D/1&2	D/3&4

NOTE: *PB12 is not available on the A/B transmitters

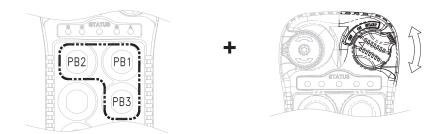
 $PB7...PB12 \rightarrow Pushbutton number$ Normal \rightarrow Normal momentary contact

4.1.4 Channel Change via Pushbuttons

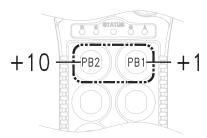
Other than the CHANNEL dipswitch on the encoder board, the transmitter channel can also be changed directly on the pushbuttons. Please refer to the instructions below on how to change the transmitter channel via pushbuttons.

1. Press and hold PB1, PB2 and PB3 and rotate the power key to the START position at the same time. A series of green and red blinks will appear on the Status LED, showing the current channel setting. A green blink represents the tens (+10) and a red blink represents the units (+1).

Examples: 2 green blinks followed by 5 red blinks represents channel 25. 6 red blinks represents channel 06.



2. Select a new channel by pressing PB1 and PB2 on the transmitter. Press PB1 to increment the units (+1) and PB2 to increment the tens (+10).



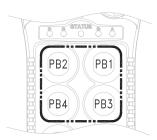
Examples: Pressing PB2 two times and then PB1 four times will give you channel 24. Pressing PB1 nine times will give you channel 09.

- 3. When finished, the newly selected channel will appear on the Status LED via a series of green and red blinks again.
- 4. Exit the channel programming by turning off the transmitter power.
- 5. Make sure the receiver channel is set identical to the transmitter. **See Section 4.2.1** on page 40 and **Section 4.2.3** on page 44 on how to change the receiver channel.
- 6. Please note that when the CHANNEL dipswitch inside the transmitter is changed, the priority will revert back to the new channel set on the CHANNEL dipswitch.
- 7. Please note that when the channel is set beyond channel 62 via PB1 and PB2 (i.e., channel 63, 68, 88, etc.), the system will recognize it as channel 62.

4.1.5 Optional 4-Digit Security Code

The 4-digit security code is an optional feature that can be programmed into the transmitter to allow operation only to those who know the code. If this feature is desired, set up as follows: Prior to rotating the transmitter power key switch to the START position to begin operation, you must first enter a 4-digit security code in order to proceed. When this 4-digit security code is entered correctly, a green light will appear on the Status LED. See the instructions below on how to program the 4-digit security code.

1. Release the E-Stop, and then press and hold PB1, PB2, PB3 and PB4 simultaneously. Rotate the power key to the START position.





- 2. A solid orange light will appear on the Status LED indicating that you are in the security code programming mode.
- 3. For newly purchased systems with the security code function deactivated (default setting), press PB1 four times (1111) to activate the security code function. At this time the Status LED on the transmitter will slowly blink orange, indicating that the 4 digits entered are correct. Then select your own 4-digit security code by pressing PB1, PB2, PB3 or PB4 on the transmitter (four presses randomly). At this time, fast orange blinks are displayed on the Status LED, telling you to reconfirm the 4-digit security code you have just entered. A green light will appear once you have re-entered the same 4-digit security code (programming completed). If any mistake is made during this process, or if a red light illuminates on the Status LED after you have re-entered the security code (incorrect input), or even if you believe you have entered the correct code but the transmitter fails to work properly, then you must reset the transmitter power (by power-cycling the transmitter*) and then repeat steps a, b, and c.

NOTE: *To power-cycle the transmitter, you must first remove and then reinstall the batteries. Simply turning the power switch off and then on will NOT properly clear the memory. This process must be used for any errors regarding proper transmitter operation (not just for security code settings).

Steps: Press and hold PB1 - PB4 and rotate the power key to the START position \rightarrow solid orange \rightarrow press PB1 four times (for new systems) or 4-digit security code \rightarrow slow orange blinks \rightarrow enter the new 4-digit security code \rightarrow fast orange blinks \rightarrow re-enter the same 4-digit security code \rightarrow green light.

- 4. If you wish to cancel the security code function, then repeat steps a, b, and c and press PB1 four times as your new security code (security code function disabled).
- 5. If you do not remember the 4-digit security code, you must contact your dealer or distributor for further assistance.

4.1.6 I-CHIP

The I-CHIP functions in a way that is very similar to a SIM card inside a mobile phone, which stores system information such as your telephone number, account number, phone book and other settings. The I-CHIP works exactly the same way, as it stores information such as system serial number/ID code, channel configurations and pushbutton configurations.

When replacing a transmitter handset, remove the I-CHIP from the old transmitter and install it into the new one (**see Fig. 16**). For a complete information transfer, make sure both the Channel and Function dipswitches are set to all "1". If both dipswitches are set to all "1", then the transmitter will operate according to the pushbutton configurations and channel stored inside the I-CHIP. If both the Channel and Function dipswitches are set to values other than all "1", then the transmitter will operate according to the channel and pushbutton configurations set on these two dipswitches rather than the ones stored inside the I-CHIP. Every time the settings on these two dipswitches are changed, the new settings will be stored into the I-CHIP automatically. In this case the previous channel and pushbutton configurations stored inside the I-CHIP will be erased and will be replaced by the new settings.

For safety purposes, the system serial number/ID code stored inside the I-CHIP cannot be changed directly on the transmitter encoder board. Only channels and pushbutton configurations can be changed directly on the encoder board via Channel and Function dipswitches. There are only two ways to change a transmitter serial number/ID code:

- via the I-CHIP programming port located on the decoder module inside the receiver unit (see Section 4.2.6 on page 50 on how to program the I-CHIP (serial number/ID code) via receiver unit
- via an external I-CHIP programmer or duplicator unit available from the factory.
 Please ask your local dealers for assistance if your system requires serial number/ID code adjustments.

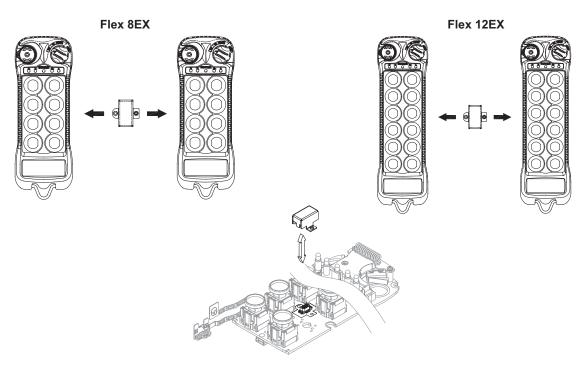


Fig. 16

4.2 Receiver Unit

4.2.1 System Channel Settings

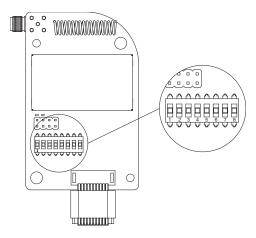


Fig. 17

Even though the Flex system is equipped with an automatic channel scanning receiver, the user can also set the receiver channel manually. **See Section 4.2.3 on page 44** for information on using the automatic channel scanning receiver.

Set the receiver channel by adjusting the channel dipswitch located on the receiver module (see Fig. 17) Only the first six (6) positions are used for channel programming (see Fig. 18). The system channels table in Section 5 on page 52 illustrates which dipswitch setting corresponds to which channel. Once the receiver channel is altered, be sure to change the transmitter channel as well. The channel on both the transmitter and the receiver must be identical in order for the system to work. To change the transmitter channel, see Section 4.1.1 on page 24.

Example:

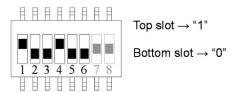


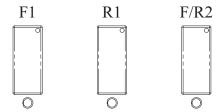
Fig. 18

The above dipswitch setting "1 0 0 1 0 0" corresponds to "channel 36" in the system channels table in **Section 5 on page 52**.

4.2.2 Output Relay Configurations

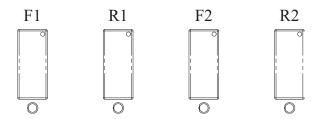
4.2.2.1 Output Relay Types

1. 3 output relays per motion – shared 2nd speed output relay
Output relays with Forward 1st speed (F1), Reverse 1st speed (R1) and Forward/
Reverse 2nd speed (F/R2). Forward and Reverse 2nd speed (F/R2) share the same output relay.



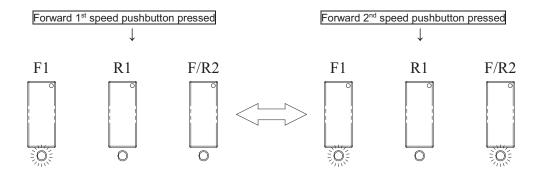
2. 4 output relays per motion – separate 1st and 2nd speed output relays

Output relays with Forward 1st speed (F1), Reverse 1st speed (R1), Forward 2nd
speed (F2) and Reverse 2nd speed (R2). Forward and Reverse 2nd speed with
separate output relays.

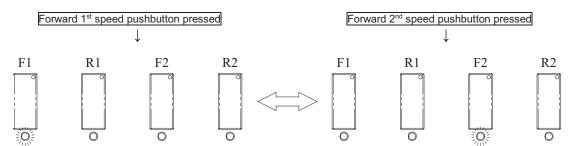


4.2.2.2 Output Relay Actions at 2nd Speed

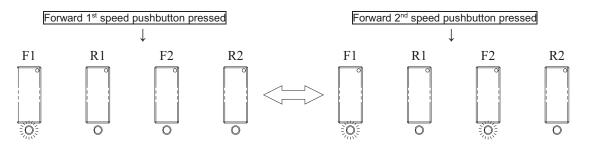
3 output relay configuration with Closed/Closed contact at 2nd speed*
 At 2nd speed, both 1st speed (F1 or R1) and 2nd speed (F/R2) output relays are closed.



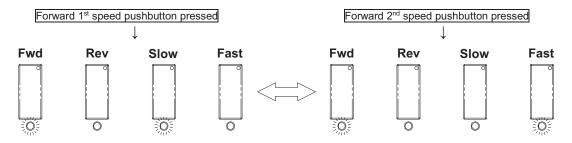
2. 4 output relay configuration with Opened/Closed contact at 2nd speed*
At 2nd speed, only the 2nd speed (F2 or R2) output relay is closed.



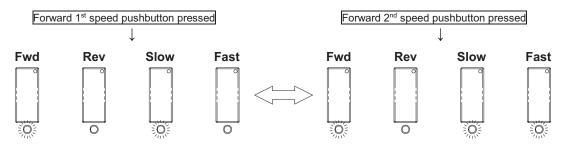
3. 4 output relay configuration with Closed/Closed contact at 2nd speed* At 2nd speed, both 1st speed (F1 or R1) and 2nd speed (F2 or R2) output relays are closed.



4. 4 output relay configuration with Forward and Fast output relays engaged at 2nd speed*



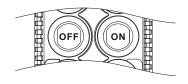
5. 4 output relay configuration with Forward, Slow, and Fast output relays engaged at 2nd speed*



NOTE: See Section 4.2.4 on page 45 on how to set this function.

4.2.2.3 ON/OFF Pushbutton Function

The user can set any of the two adjacent pushbuttons on the transmitter to behave like a mechanical ON & OFF rocker switch (see Section 4.2.4 on page 45 on how to set to this function). When the ON output relay is closed (ON pushbutton pressed), the OFF output relay will open automatically, or vice versa.



4.2.2.4 START/AUX Function

After initiating the START function, the START position will become an auxiliary function with momentary contact. For an auxiliary application such as a horn or a buzzer, connect it to the FUNC output relay (wire #6) located inside the receiver unit.

4.2.2.5 Brake Function

When the transmitter pushbutton is released from 2nd speed up to 1st speed, both 1st and 2nd speed output relays will open for up to 1 second and then with 1st speed output relay closed thereafter (see Section 4.2.4 on page 45 on how to set to this function).

4.2.2.6 Momentary Contact

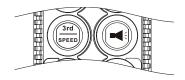
When a pushbutton is released, the output relay corresponding to that pushbutton will open (**see Section 4.2.4 on page 45** on how to set to this function). This type of contact usually applies to external applications such as horns or buzzers.

4.2.2.7 Toggled Contact

When a pushbutton is released, the output relay corresponding to that pushbutton will remain closed (maintain contact) until the next time the user presses the same pushbutton (**see Section 4.2.4 on page 45** on how to set to this function). This type of contact is usually applied to external applications such as lights.

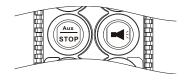
4.2.2.8 3rd Speed Pushbutton Function

This function allows the crane to travel an additional step beyond 2nd speed. For example, if the operator is pressing the UP pushbutton down to 2nd speed, pressing the 3rd speed pushbutton (with UP pushbutton still held at 2nd speed) will toggle between 2nd speed and 3rd speed (see Section 4.2.4 on page 45 on how to set to this function).



4.2.2.9 Auxiliary STOP Pushbutton Function

The auxiliary STOP function acts as a 2nd emergency stop button. Other than by emergency stop button and transmitter power key switch, the receiver MAIN is also deactivated when this auxiliary stop pushbutton is pressed (**see Section 4.2.4 on page 45** on how to set to this function).

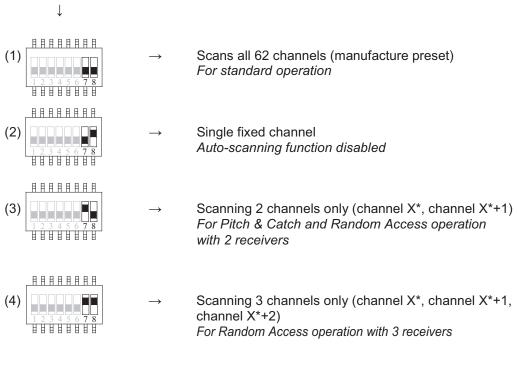


4.2.2.10 Pitch & Catch Function

This function allows two operators to control one crane from opposite ends of a cross or long travel (**see Section 4.2.4 on page 45** on how to set to this function). When set to "Pitch & Catch" make sure the 2nd transmitter is set to the next-highest channel (channel X*+1). For example, if the system is preset at Ch. 01 then the channel of the 2nd transmitter should be set to Ch. 02. Furthermore, dipswitch positions #7 and #8 on the receiving module should be set to "10". This will allow the receiver to scan only Ch. 01 and Ch. 02. On the other hand, since there are only 62 available channels on the Flex system, the system preset at channel 62 is ineffective because the 2nd transmitter cannot be set to Ch. 63. If your system is preset at Ch. 62, be sure to change it to another channel.

4.2.3 Receiver Auto-Scanning Settings

Receiver Channel Dipswitch



^{*} Channel X → Channel set on the receiving module

Example: If the first 6 dipswitch positions on the receiving module are set to Ch. 01 ("000000" or "000001"), when set to 2-channel scanning (type 3 above), then the receiver will only scan Ch. 01 and Ch. 02.

4.2.4 Dipswitch Settings

4.2.4.1 Interlocked Functions

Interlocked means the two adjacent pushbuttons cannot be activated simultaneously as they will cancel each other out when pressed. Interlocked settings usually apply to a crane's forward and reverse motions. Each dipswitch on the decoder module corresponds to one (1) motion or two (2) adjacent pushbuttons (see Fig. 19, Fig. 20 and Fig. 21). Only the first seven (7) dipswitch positions are used (counting from left to right). The 8th dipswitch position (far right) is not used.

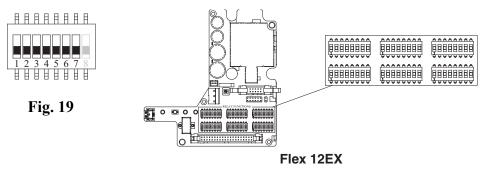


Fig. 20

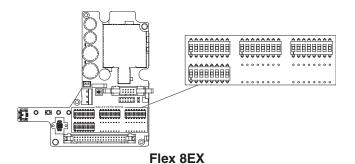


Fig. 21

Manufacture preset

Dip Settings	Function Descriptions	# of Relays Used
0000000	Normal (single speed only, F2 & R2 relays not used)	2
0000001	Closed/Closed Relay Action at 2nd Speed (separate 2nd speed relay)	4
0000010	Closed/Closed Relay Action at 2nd Speed (shared 2nd speed relay)	3
0000011	Opened/Closed Relay Action at 2nd Speed (separate 2nd speed relay)	4

Manufacture preset

Dip Settings	Function Descriptions	# of Relays Used
0000100	Forward and Fast output relays engaged at 2nd speed	4
0000101	Forward, Slow, and Fast output relays engaged at 2nd speed	4
0000110	ON (right button) & OFF (left button)	2
0001000	ON & OFF - affected by the E-Stop command. When E-Stop command is initiated, the OFF relay is activated.	2
0001001	ON + START / OFF + START - Prior to pressing the button you must first rotate and hold the power key switch at the START position to activate ON or OFF relays.	2
0001010	FWD/REV toggled (latched)	2
0001011	FWD/REV toggled (latched) and affected by the E-Stop command	2
0100001	Closed/Closed + Brake	4
0100010	Closed/Closed Relay Action + Brake	3
0100011	Opened/Closed Relay Action + Brake	4

4.2.4.2 Non-Interlocked Functions

Unlike interlocked settings, non-interlocked settings allow the two adjacent pushbuttons to be used simultaneously. Non-interlocked settings are usually applied to a crane's auxiliary functions such as lights, horns, 3rd speed, auxiliary stop, and Pitch & Catch. Each dipswitch on the decoder module corresponds to one (1) motion or two (2) adjacent pushbuttons (left and right pushbuttons).

Function Code	Dip Position Setting #1	Dip Position Setting #2 - #4 (left button) and #5 - #7 (right button)	Function Description
Α	1	000	Normal (momentary) contact
В	1	001	Toggled (latching) contact
С	1	010	Acceleration (3rd speed)
D	1	011	Toggled (latching) contact affected by the E-Stop command. When E-Stop command is initiated, all toggled (latching) relays are also deactivated.
E	1	101	Pitch & Catch Type 1. When Pitch (release) function is initiated, receiver MAIN will not be deactivated.
F	1	110	Pitch & Catch Type 2. When Pitch (release) function is initiated, receiver MAIN will be deactivated.
G	1	111	Auxiliary Stop
н	1	100	Normal + Start function. For added safety, you must first rotate and hold the power key switch at the START position and then press the intended pushbutton at the same time to activate the output relay.

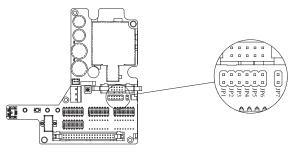
Example #1: Left button (set to function code A) / right button (set to function code A) \rightarrow 1 000 000 Example #2: Left button (set to function code B) / right button (set to function code B) \rightarrow 1 001 001 Example #3: Left button (set to function code A) / right button (set to function code C) \rightarrow 1 000 010 Example #4: Left button (set to function code E) / right button (set to function code A) \rightarrow 1 101 000

NOTE: When set to Pitch & Catch function, make sure the 2nd transmitter is set to the next-highest channel. For example, if the system is preset at Ch. 01, then the 2nd transmitter should be set to Ch. 02. Furthermore, you must also set the dipswitch on the receiving module (positions #7 and #8) to the "10" position (2-channel scanning) (see Section 4.2.2.10 on page 44).

NOTE: When set to "Auxiliary Stop", be sure JP3 is inserted (see Section 4.2.5 on page 48).

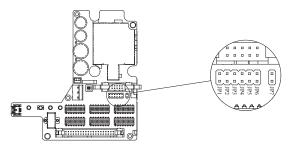
4.2.5 Jumper Settings

Jumper settings are applied to functions such as mainline-disconnect time, Start function, transmitter pushbutton layout, system information (serial number/ID code) programming, and system testing. Jumpers #1 - #7 are located on the decoder module above the four (4) (for Flex 8EX) and six (6) (for Flex 12EX) dipswitches (see Fig. 22 and Fig. 23).



Flex 8EX

Fig. 22



Flex 12EX

Fig. 23

Manufacture preset

Jumper Settings		Function	
JP3 (Blank)		After 1 minute (depending on the Continuous Transmitting Time Adjustment setting in Section 4.1.2 on page 25) of transmitter inactivity (MAIN deactivated), press any pushbutton on the transmitter to reactivate the receiver MAIN.	
JP3 (Inserted)		After 1 minute (depending on the Continuous Transmitting Time Adjustment setting in Section 4.1.2 on page 25) of transmitter inactivity (MAIN deactivated), rotate the transmitter power key switch to the START position to reactivate the receiver MAIN.	
JP4 (Blank)	JP5 (Blank)	Standard right-to-left pushbutton configuration for all models	
JP4 (Inserted)	JP5 (Blank)	In-line pushbutton configuration (top to bottom) for Flex 8ES/EX	
JP4 (Blank)	JP5 (Inserted)	In-line pushbutton configuration (top to bottom) for Flex 12ES/EX	
JP4 (Inserted)	JP5 (Inserted)	In-line pushbutton configuration (top to bottom) for Flex 4ES/EX	
JP6 (Blank)		Program system serial number/ID code and channel from decoder module to I-CHIP	
JP6 (Inserted)		Program system serial number/ID code and channel from I-CHIP to decoder module	
JF (Inse		For system test only, receiver MAIN is disabled	

4.2.6 I-CHIP Programming Port

For 8EX:

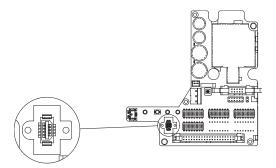


Fig. 24

For 12EX:

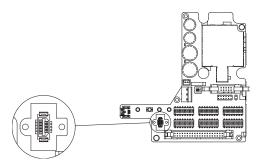


Fig. 25

The I-CHIP programming port located on the decoder module (**see Fig. 24** and **Fig. 25**) inside the receiver is designed for the purpose of transferring system serial number/ID code either from the I-CHIP to the receiver or vice versa. If you wish to transfer system information from the receiver to the I-CHIP, insert the I-CHIP onto the programming port (JP6 jumper not inserted), wait until the Status LED on the decoder module turns a solid green (within 2 seconds), and then take the I-CHIP out of the programming port (programming completed). At this time the I-CHIP should also possess the same serial number/ID code as the receiver. If the Status LED on the decoder module displays a solid red light after inserting the I-CHIP (programming failed), then you must reinsert the I-CHIP one more time. On the other hand, if you wish to transfer system information from the I-CHIP to the receiver, then you must first insert JP6 jumper prior to inserting the I-CHIP, then wait for the green light to appear on the Status LED. At this time the receiver should also possess the same system information as the I-CHIP. Please note that the receiver unit must be powered in order to proceed with the programming.

4.2.7 Voltage Settings

Always check that the voltage setting is correct for your application prior to installation (see Fig. 26).

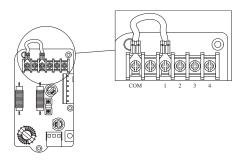


Fig. 26

Position 1 \rightarrow 110 - 120VAC

Position 2 \rightarrow 220 - 240VAC or 24VAC*

Position 3 \rightarrow 380 - 400VAC or 42VAC*

Position 4 \rightarrow 410 - 460VAC or 48VAC* or 12 - 24VDC**

* For system with 24/42/48VAC power supply

* For system with 12 - 24VDC power supply

Fuse Ratings:

FUSE#	110 - 120VAC	220 - 240VAC	380 - 400VAC	410 - 460VAC	24VAC	42 & 48VAC	12 - 24VDC
F1 - F8	5.0A (clear)	5.0A (clear)	5.0A (clear)				
F9 - F10	1.0A (red)	1.0A (red)	1.0A (red)	0.5A (blue)	3.0A (yellow)	2.0A (purple)	2.0A (purple)

5 System Channels Table

Channel	Frequency	Dipswitch Setting	Channel	Frequency	Dipswitch Setting
01	433.000MHZ	000000	32*	433.775MHZ	100000
01	433.000MHZ	000001	33*	433.800MHZ	100001
02	433.025MHZ	000010	34*	433.825MHZ	100010
03*	433.050MHZ	000011	35*	433.850MHZ	100011
04*	433.075MHZ	000100	36*	433.875MHZ	100100
05*	433.100MHZ	000101	37*	433.900MHZ	100101
06*	433.125MHZ	000110	38*	433.925MHZ	100110
07*	433.150MHZ	000111	39*	433.950MHZ	100111
08*	433.175MHZ	001000	40*	433.975MHZ	101000
09*	433.200MHZ	001001	41*	434.000MHZ	101001
10*	433.225MHZ	001010	42*	434.025MHZ	101010
11*	433.250MHZ	001011	43*	434.050MHZ	101011
12*	433.275MHZ	001100	44*	434.075MHZ	101100
13*	433.300MHZ	001101	45*	434.100MHZ	101101
14*	433.325MHZ	001110	46*	434.125MHZ	101110
15*	433.350MHZ	001111	47*	434.150MHZ	101111
16*	433.375MHZ	010000	48*	434.175MHZ	110000
17*	433.400MHZ	010001	49*	434.200MHZ	110001
18*	433.425MHZ	010010	50*	434.225MHZ	110010
19*	433.450MHZ	010011	51*	434.250MHZ	110011
20*	433.475MHZ	010100	52*	434.275MHZ	110100
21*	433.500MHZ	010101	53*	434.300MHZ	110101
22*	433.525MHZ	010110	54*	434.325MHZ	110110
23*	433.550MHZ	010111	55*	434.350MHZ	110111
24*	433.575MHZ	011000	56*	434.375MHZ	111000
25*	433.600MHZ	011001	57*	434.400MHZ	111001
26*	433.625MHZ	011010	58*	434.425MHZ	111010
27*	433.650MHZ	011011	59*	434.450MHZ	111011
28*	433.675MHZ	011100	60*	434.475MHZ	111100
29*	433.700MHZ	011101	61*	434.500MHZ	111101
30*	433.725MHZ	011110	62*	434.525MHZ	111110
31*	433.750MHZ	011111	I-CHIP	See Note 2	111111

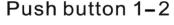
NOTE 1: Frequencies marked with * are approved for use in Australia.

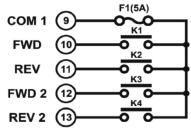
NOTE 2: When set to all "1" the priority goes to the channel assigned inside the I-CHIP.

6 Receiver Installation

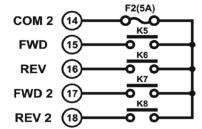
6.1 Output Relay Contact Diagrams

6.1.1 Flex 8EX

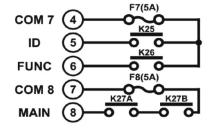




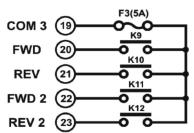
Push button 3-4



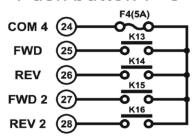
MAIN/ID/Function

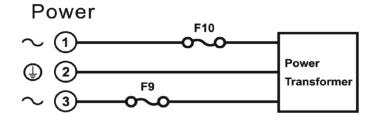


Push button 5-6



Push button 7-8

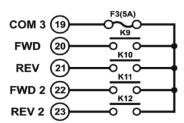




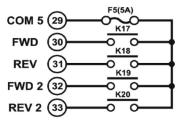
6.1.2 Flex 12EX

Push button 1-2

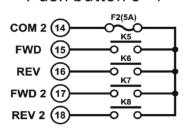
Push button 5-6



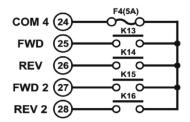
Push button 9-10



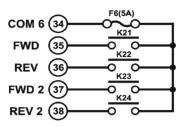
Push button 3-4



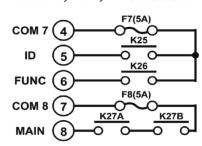
Push button 7-8

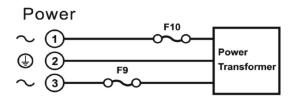


Push button 11-12







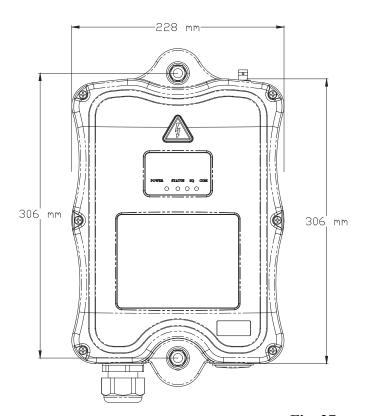


- For Flex A/B Systems, A connects to wire #26 (Flex 8EX) and wire #36 (Flex 12EX) and B connects to wire #28 (Flex 8EX) and wire #38 (Flex 12EX).
- For 3-relay (shared 2nd speed) and 4-relay (separate 2nd speed) configuration, **see Section 4.2.2.1 on page 41**.
- For 4-relay closed/closed and 4-relay opened/closed configuration, **see Section 4.2.2.2 on** page 41.
- For different voltage settings, see Section 4.2.7 on page 51.
- For F9 and F10 power fuse ratings, see Section 4.2.7 on page 51.
- For 12 24VDC power supply, wire #1 corresponds to the negative charge (-) and wire #3 corresponds to the positive charge (+). Wire #2 is for GROUND.
- Wire #6 is for "Normal Close" and wire #8 is for "Normal Open" MAIN output.
- Due to the possibility of voltage spikes on the contactors, suppressors are required on contactors being driven by Flex relays.

6.2 Pre-installation Precautions

- 1. Make sure the transmitter and the receiver have identical serial number/ID codes and channels.
- 2. Make sure the receiver is not set to the same channel as any other systems in use in the surrounding area.
- 3. Make sure that the crane or equipment is working properly prior to installation.
- 4. Make sure the power source to the receiver is set correctly.
- 5. Switch off the main power source to the crane or equipment prior to installation.

6.3 Step-by-Step Installation



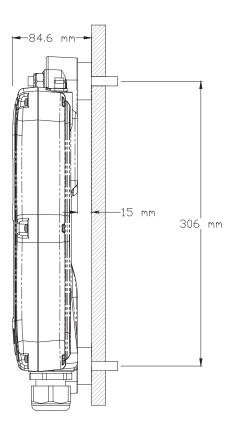


Fig. 27

- 1. For best reception, the location of the receiver should be visible to the operator at all times.
- 2. The location selected should not be exposed to high levels of electric noise. Mounting the receiver next to an unshielded variable-frequency drive may cause minor interference. Always locate the receiver as far away from a variable-frequency drive as possible.
- 3. Ensure the selected location has adequate space to accommodate the receiver. If an external antenna is used, always locate the receiver where the antenna is free from any obstacles from all directions to avoid the possibility of antenna damage (see Fig. 28).

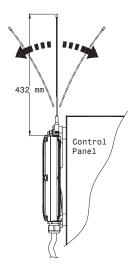


Fig. 28

4. When installing an external antenna, you must connect the SMA jack located inside the receiver and make sure to set the jumper to "EXT" position (see Fig. 29).

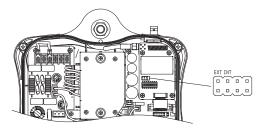


Fig. 29

- 5. For better reception, make sure the receiver is in an upright position.
- 6. Drill two holes (10 mm in diameter) on the control panel or location where the receiver is to be installed (**see Fig. 27**).
- 7. Make sure the two bolts are tightened after installation.
- 8. Install suppressors on all contactors being driven by Flex relays. This is due to the possibility of voltage spikes on the contactors.
- 9. For system wiring, see Section 6.1 on page 53.

6.4 System Testing

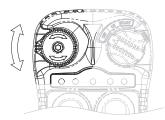
- 1. Turn on the power source to the receiver and test the MAIN relay output by pressing the red emergency stop button and observe that it properly opens and closes the mainline disconnect contactor.
- 2. Test the operation of each function to ensure it corresponds to the transmitter direction labels or the pendant it is replacing.
- 3. Test the limit switches (if any) to see if they are working properly.
- 4. If your new remote control is replacing an existing pendant, make sure it is completely disconnected and placed in a safe location to prevent unwanted control commands.

7 Operating Procedure

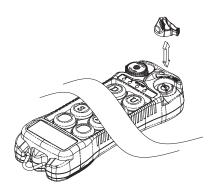
7.1 Transmitter Operation

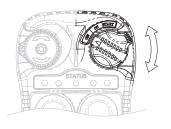
7.1.1 General Operating Procedure

1. Reset the red emergency stop button located on the top left side of the transmitter handset by rotating it either clockwise or counterclockwise. The red button will pop up.



2. Turn on the transmitter power by inserting the black-colored key into the power key slot (located on the top right side of the transmitter handset) and rotate it clockwise to the ON position.





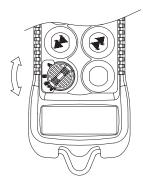
- 3. After turning on the transmitter power, check the Status LED on the transmitter handset for any sign of system irregularities (**see Section 7.2 on page 62**). If the system is normal, the Status LED will illuminate green for 2 seconds.
- 4. If there are no signs of any system irregularities, then continue to rotate the power key switch clockwise to the START position for up to 2 seconds (depending on JP3 setting; see Section 4.2.5 on page 48). This will activate all transmitter pushbutton functions as well as the receiver MAIN. Thereafter, the same START position will become an auxiliary function with momentary contact (see Section 4.2.2.6 on page 43).



- 5. In case of an emergency, pressing down the red emergency stop button will immediately disconnect the receiver MAIN as well as the transmitter power. To resume operation, rotate the red button clockwise or counterclockwise until it pops up. Then, rotate the power key switch to the START position for up to 2 seconds to resume operation (depending on JP3 setting; see Section 4.2.5 on page 48). Please note that every time you turn the transmitter power off and back on again, or after resetting the emergency stop button, all pushbutton functions will be locked to avoid any unintentional controls. For safety, initiating the START command after turning on the transmitter power or after resetting the emergency stop button is strictly required.
- 6. After 1 minute of inactivity, the receiver MAIN will be disconnected temporarily. To resume operation, rotate the power key to the START position (depending on JP3 setting; see Section 4.2.5 on page 48). Refer to the Continuous Transmitting Time Adjustment setting in Section 4.1.2 on page 25 if this 1-minute inactivity time is not sufficient for your application. Also, the receiver MAIN will be disconnected temporarily when the receiver encounters strong radio interference or when the operator is controlling the crane or equipment beyond the transmitting range.
- 7. Turn off the transmitter power by rotating the power key counterclockwise to the OFF position. It will disconnect the transmitter power and the receiver MAIN altogether. Continue to turn it counterclockwise to release the key.

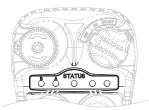
7.1.2 Rotary Select A/B Operating Procedure

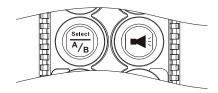
This changeover function is designed specifically for crane systems with dual hoists and/or trolleys. Switch between the main and auxiliary hoists simply by rotating the selector switch to either A, B, or A+B. For system wiring, **see Section 6.1 on page 53**.



7.1.3 A/B Selector Pushbutton Operating Procedure

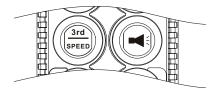
Pressing the "Select A/B" pushbutton will toggle between output relay A, B, and A+B, respectively. There are 4 different types of Select A/B sequences available; **see Section 4.1.3.2 on page 27** for instructions on how to set Select A/B functions.





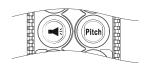
7.1.4 3rd Speed Pushbutton Operating Procedure

When a pushbutton is held at 2nd speed, pressing the 3rd speed pushbutton one time will activate the 3rd speed output relay (toggled). If the operator wants 2nd speed again, press the 3rd speed pushbutton one more time.



7.1.5 Pitch & Catch Operating Procedure

To release control of the crane, press the "Pitch" pushbutton. To take over control of the crane, rotate the power key switch to the "Catch" position for up to 2 seconds. The 2nd operator cannot take control of the crane unless the 1st operator presses the "Pitch" pushbutton (2 seconds). If the operator unintentionally presses the "Pitch" pushbutton during operation, rotate the power key to the "Catch" position for up to 2 seconds to regain control.







7.1.6 Automatic Channel Scanning Operating Procedure

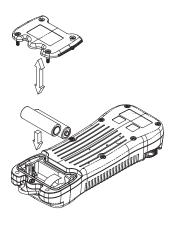
After changing the transmitter channel (**see Section 4.1.1 on page 24**), turn on the transmitter power, rotate the power key switch to the START position and hold it there for up to 1 minute. Within this 1-minute period, the receiver will search (channel 01 - channel 62) and lock onto the newly selected transmitter channel automatically. Please note that in order for the receiver to switch to auto-scanning mode, prior to changing the transmitter channel, you must first deactivate the receiver MAIN by shutting off the transmitter power or press down the emergency stop button. **See Section 4.2.3 on page 44** if you do not want the receiver to auto-scan all 62 channels.

Change Transmitter Channel



7.1.7 Changing Transmitter Batteries

Change the transmitter batteries by unscrewing the battery cover located on the backside of the transmitter (**see Fig. 30**). During battery installation, make sure that the blue ribbon is centered between the two batteries. After changing the batteries, also make sure that all screws are tightened to avoid water, moisture, dirt, grease, or other liquid penetration.



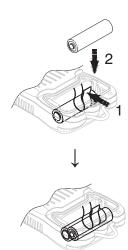


Fig. 30

7.2 Status Light Indicators and Warnings

7.2.1 Transmitter STATUS Light Indication

Туре	Display Type	Indication
		Voltage goes below 1.9V at initial power on - transmitter power shuts off.
1	Solid red	Voltage goes below 1.8V during operation - transmitter power and receiver MAIN shut off.
2	1 red blink followed by a 2- second pause	Voltage goes below 1.85V during operation - change batteries immediately.
3	2 red blinks followed by a 2- second pause	The pushbutton is defective after turning on the transmitter power.
4	No light displayed	When a defective pushbutton condition occurs (2 red blinks, type 3 above), find out which pushbutton is defective by pressing all the pushbuttons on the transmitter one at a time. If the pushbutton is in good working order, the LED will not light up when pressed. If the pushbutton is defective, the LED will continue to display 2 red blinks when pressed.
5	3 red blinks followed by a 2- second pause	EEPROM error
6	4 red blinks followed by a 2- second pause	Transmitting error; system cannot lock on to the designated channel.
7	Solid green for up to 2 seconds	Transmitter power on with no faults detected (prior to initiating the START function)
8	Blinking green	Transmission in progress
9	Slow red blinks	Stop command initiated with receiver MAIN deactivated
10	1 orange blink every 4 seconds	Transmitter on standby
11	Alternate red and green blinks	I-CHIP has lost programming. Reprogram the I-CHIP.

7.2.2 Receiver STATUS Light Indication

Туре	Display Type	Indication
1	Fast green blinks	Decoding in process
2	Slow green blinks	Decoding on standby
3	Slow red blinks	Stop command initiated with receiver MAIN deactivated
4	2 red blinks	Receiver MAIN jammed or defective
5	Fast red blinks	Incorrect transmitter serial number/ID code
6	Solid red	Receiver under-voltage, LV output relay activated
7	No light displayed	Decoding microprocessor is defective

7.2.3 Receiver SQ Light Indication

Type	Display Type (Red)	Indication
1	ON (fast blinks)	Transmission received
2	Off	No transmission
3	Blinks intermittently	Other radio interference

7.2.4 Receiver POWER Light Indication

Туре	Display Type (Red)	Indication
1	On	Power to receiver
2	Off	No power to receiver

7.2.5 Receiver COM Light Indication

Туре	Display Type (Red)	Indication
1	On	Power to relay board
2	Off	No power to relay board

7.3 Troubleshooting Tips

Problems	Possible Reasons	Suggestions
	Transmitter low battery power	Check the transmitter battery level.
	Emergency stop button activated prior to startup	Prior to turning on the transmitter power switch, make sure the red emergency stop button is elevated.
No response when	Improper startup pro- cedure (8EX)	Redo the startup procedure by holding the power key at the START position for up to 2 seconds and then release.
transmitter push- button is pressed (improper startup	Transmitter pushbut- ton functions locked (12EX)	Initiate the Start command by rotating the power key switch to the START position.
and settings)	Incorrect system RF channel	Check and make sure the transmitter handset and the receiver unit both have the same channel.
	Incorrect system serial number/ID code	Check and make sure the transmitter handset and receiver unit both have the same serial number/ID code.
	System out of range	Make sure the startup procedure is initiated within 100 meters (300 feet) from the receiver location.
No response when transmitter push- button is pressed (damaged hard- ware)	Defective transmitting and receiving module	Check the SQ display on the face of the receiver unit. If it does not illuminate when the pushbutton is pressed, then either the transmitting or receiving module is defective. First, replace the transmitting module. If the SQ display is still not lit when the pushbutton is pressed, then replace the receiving module.
,	Defective encoder board or decoder module	If still no response, replace the transmitter encoder board. If it is still unresponsive, then the decoder module is defective.
No AC novembre the	Incorrect input voltage	Make sure the source voltage is set correctly.
No AC power to the receiver	Blown fuse	Check for any blown fuse.
	Incorrect wiring	Check input voltage connection.
Outputs do not correspond to transmitter	Incorrect output connection	Check the system wiring again. Please refer to the output contact diagram inside this manual or on the receiver cover.

8 System Specifications

Frequency Range: 433 - 434 MHz
Frequency Deviation: 12.5 KHz
Number of Channels: 62 channels

Modulation: Digital Frequency Modulation based on Manchester Code.

20-bit address, 32-bit CRC Parity Check and Hamming Code.

Encoder & Decoder: Microprocessor-controlled
Transmitting Range: >100 meters (300 feet)

Frequency Control: Synthesized PLL (Phase Lock Loop)

Receiver Type: Frequency Auto Scanning

Receiver Sensitivity: -116 dBm
Antenna Impedance: 50 ohms

Responding Time: 60 milliseconds (average)

Transmitting Power: 1.0 mW
Enclosure Type: NEMA-4X

Enclosure Rating: IP66

Output Contact Rating: 250V @ 8 Amps

Transmitter Operating Voltage: 3.0VDC
Receiver Power Consumption: 11.0 VA

Receiver Supply Voltage: <u>Voltage Setting</u> <u>Min - Max</u>

24VAC (22 - 26VAC) 42VAC (38 - 46VAC) 48VAC (43 - 53VAC) 110VAC (104 - 126VAC) 220VAC (207 - 253VAC) 380VAC (351 - 429VAC) 410VAC (400 - 480VAC) 12/24VDC (9 - 36VDC)

Operating Temperature: -25°C - 75°C / -13°F - 167°F

Transmitter Dimension: 8EX: 184 mm (L) x 69 mm (W) x 34 mm (H)

12EX: 230 mm (L) x 69 mm (W) x 35 mm (H)

Receiver Dimension: 306 mm (L) x 228 mm (W) x 84.6 mm (H)

Transmitter Weight: 8EX: 242 g / 8.5 oz

12EX: 296 g / 10.4 oz

Receiver Weight: 2.5 kg / 5.5 lb

9 Declaration of Conformity



For the following equipment:

Product : Flex Series Radio Remote Control

Multiple Listee Model No. : Flex 4ES/EX/EM, Flex 6EX, Flex 8ES/EX/EM, Flex 12ES/EX/EM, Flex 8/12 PRO

Product Receiver Models : CAN-2, MHR, WIC-2402, Flex 4 RX, Flex 6 RX, Flex 8R X, Flex 12 RX

Transmitter Model Serial Number : Receiver Model Serial Number : Manufacturer's Name : Magnetek, Inc.

Manufacturer's Address : N49 W13650 Campbell Drive Menomonee Falls, WI 53051 USA

The undersigned hereby declares on behalf of Magnetek, that the above-referenced products, to which this declaration relates, is in conformity with the provisions of CE Mark Directive (93/68/EEC), Machinery Safety Directive (MD, 2006/42/EC), Radio Equipment Directive (RED, 2014/53/EU), EMC Directive (2014/30/EU), and the ROHS2 Directive (2011/65/EU).

The standards relevant for the evaluation of the product referenced above conformity to the directive requirements are as follows:

EN 301 489-1 v2.2.0:2017-03 EN 60204-32:1998
EN 301 489-3 v1.4.1:2002-04 EN 60529:1992
EN 301 489-17 v2.1.1:2009-05 EN 12100:2010
EN 300 328 v2.1.1:2016-11 EN ISO 13849-1:2008
EN 300 220-1 v2.3.1:2010 EN ISO 13849-2:2012
EN 300 220-2 v2.3.1:2010 EN 13557:2003+A2:2008
EN 60204-1:2006+A1:2009

The European contact for Magnetek is:

Brian Preston
Magnetek

Unit 3, Bedford Business Centre

Mile Road Bedford MK42 9TW United Kingdom

Per Annex II.B of the Machinery Directive (2006/42/EC):

The machinery, product, assembly or sub-assembly covered by this Declaration of Conformity must not be put into service until the machinery into which it is to be incorporated has been declared in conformity with the provisions of the applicable Directive(s). This statement is only necessary where the product is to be incorporated into a machine or system (e.g. a safety component).

Signature of Authorized Person:

Travis Tedesco
Engineering Development Manager
Columbus McKinnon Corporation

hum for M

Bridgeville, PA USA

Date of Issuance: 31 January 2019

Director of Development Columbus McKinnon Corporation

Menomonee Falls, WI USA

Peter Stipan